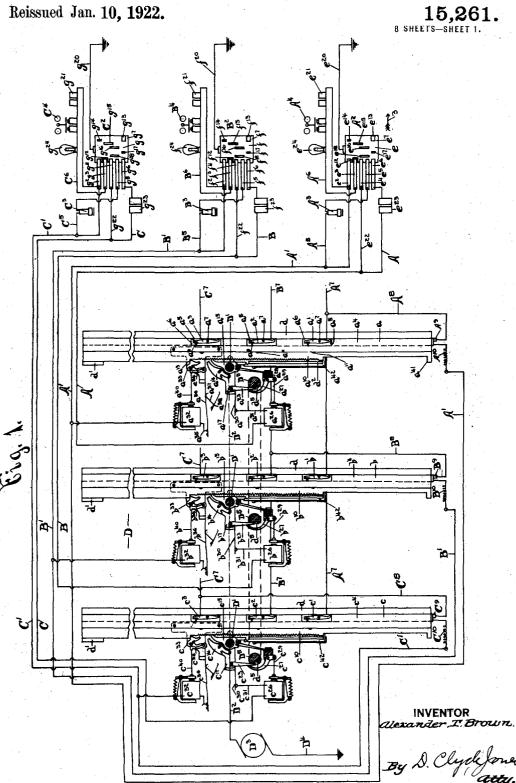
A. T. BROWN. ELECTRIC EXCHANGE SYSTEM. APPLICATION FILED AUG. 16, 1921.

Reissued Jan. 10, 1922.



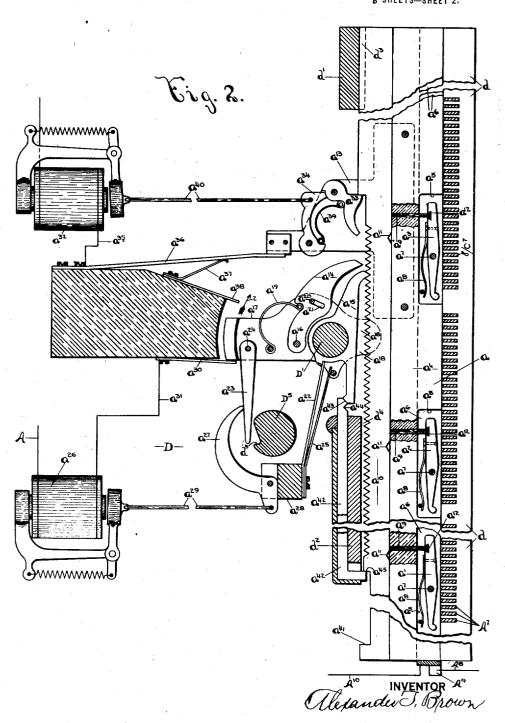
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15,261. 8 SHEETS-SHEET 2.



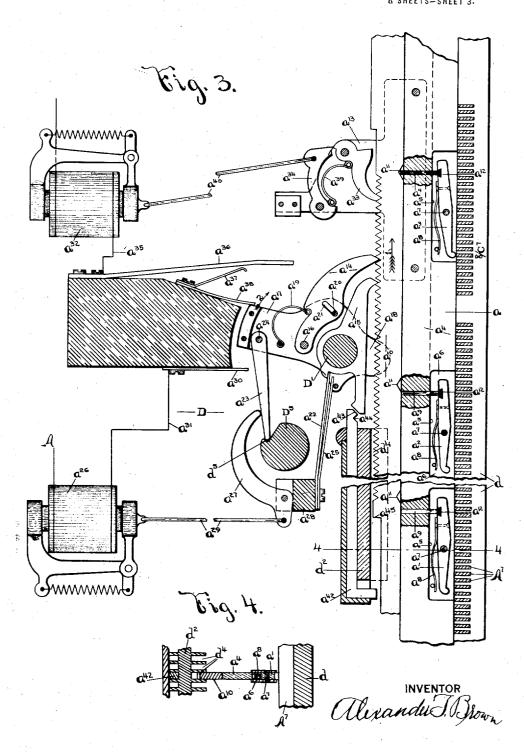
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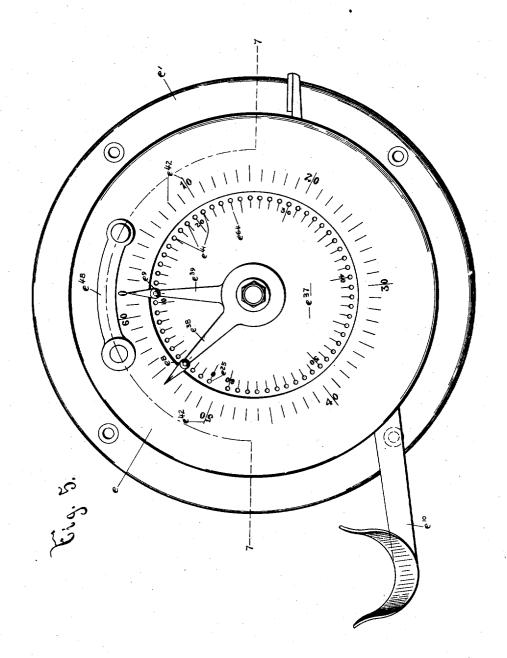
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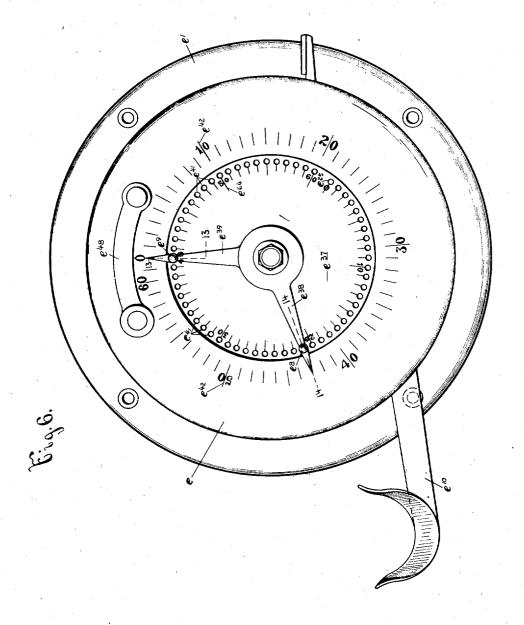
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. INVENTOR Clerander Bloan A. T. BRUWN.
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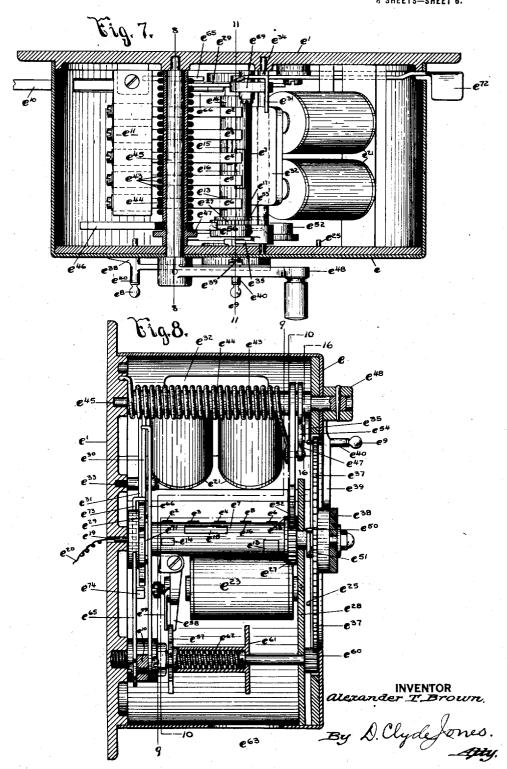


INVENTOR Alexander J. Brown

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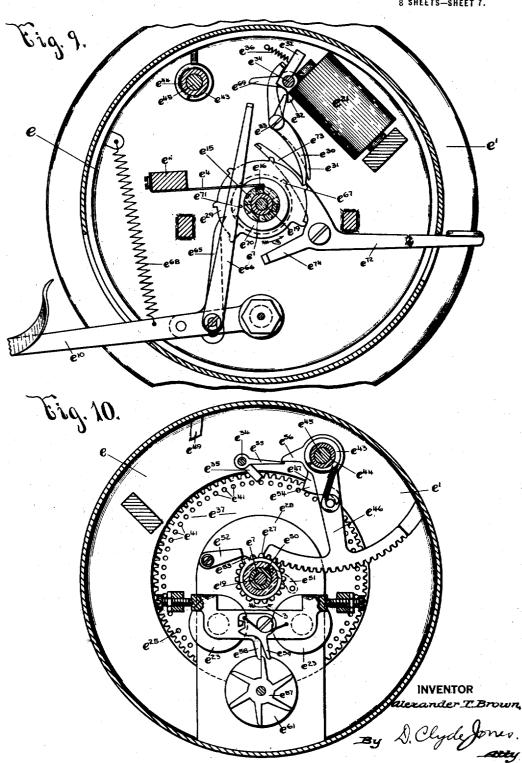
15,261. 8 SHEETS-SHEET 6.



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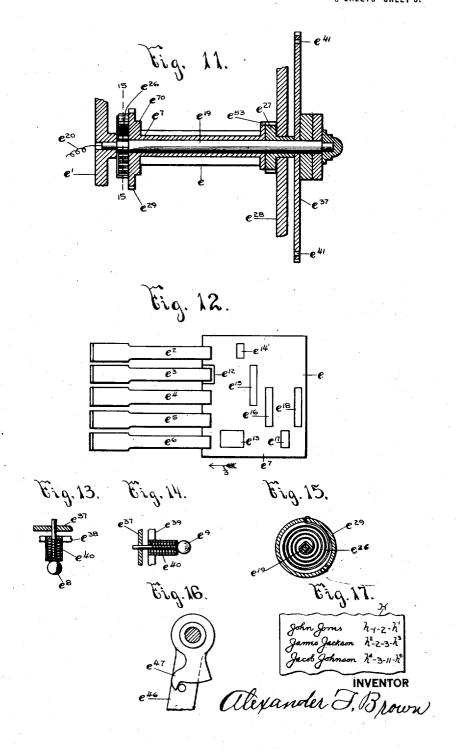
15,261. 8 SHEETS-SHEET 7.



# A. T. BROWN. ELECTRIC EXCHANGE SYSTEM. APPLICATION FILED AUG. 16, 1921.

Reissued Jan. 10, 1922.

15,261. 8 SHEETS-SHEET 8.



## UNITED STATES PATENT OFFICE.

ALEXANDER T. BROWN, OF SYRACUSE, NEW YORK, ASSIGNOR, BY MESNE ASSIGN-MENTS, TO STROMBERG-CARLSON TELEPHONE MANUFACTURING COMPANY, OF ROCHESTER, NEW YORK, A CORPORATION OF NEW YORK.

#### ELECTRIC EXCHANGE SYSTEM.

15,261.

Specification of Reissued Letters Patent. Reissued Jan. 10, 1922.

Original No. 992,333, dated May 16, 1911, Serial No. 550,933, filed May 28, 1895. Renewed July 16, 1910. Serial No. 572,282. Application for reissue filed August 16, 1921. Serial No. 492,852.

To all whom it may concern:

Be it known that I, ALEXANDER T. BROWN, of Syracuse, in the county of Onondaga, in the State of New York, have invented new 5 and useful Improvements in Electric Exchange Systems, of which the following, taken in connection with the accompanying drawing, is a full, clear, and exact descrip-

My invention relates to improvements in electric exchange systems for permitting automatic communication between different circuits as telephonic, telegraphic, &c., and has for its object the production of a simple 15 and practical apparatus for accomplishing the desired result, which is highly effective in operation and necessitates in its use but a minimum degree of skill and manipulation; and to this end it consists essentially in the 20 construction, arrangement, and electric connection of the component parts of the system, all as hereinafter more fully described and pointed out in the claims.

In describing this invention, reference is 25 had to the accompanying drawing, forming a part of this specification, in which like letters and numerals indicate corresponding

parts in all the views.

Figure 1 is a diagrammatic view illus-30 trating the general construction and arrangement of an electric exchange system embodying my invention. Fig. 2 is an elevation partly in section, of one of the detached switching apparatus of the system, shown in 35 its normal position. Fig. 3 is an elevation, partly in section, of the switching apparatus seen in Fig. 2, which is here shown in operative position. Fig. 4 is a detail section taken on line 4—4, Fig. 3. Fig. 5 is a face view 40 of one of the controlling devices of the system, its indicators being shown in their position assumed for effecting the movement of the corresponding switching apparatus to the position assumed by the switching ap-45 paratus in Fig. 3. Fig. 6 is a face view of the controlling device seen in Fig. 5, its indicators being illustrated in a different position from that assumed in Fig. 5. Fig. 7 is a horizontal section, taken on line 7—7, 50 Fig. 5. Fig. 8 is a vertical section, taken on line 8-8, Fig. 7. Figs. 9 and 10 are ver-

Fig. 8. Fig. 11 is a detail section, taken on line 11-11, Fig. 7. Fig. 12 is a top plan 55 view of the brushes or terminals of one of the controlling devices, and the terminal support for engaging said brushes or terminals shown diagrammatically as a flat plate. Figs. 13 and 14 are detail sections, taken, 60 respectively, on lines 13—13 and 14—14, Fig. 6. Figs. 15 and 16 are detail sections, taken respectively on lines 15—15 and 16—16, Figs. 11 and 8; and Fig. 17 is a detail elevation of a part of an index suitable 65

for use with my improved system.

In my improved electric exchange system, each circuit for which automatic connection is desired is provided with a switching apparatus for connecting the same with the 70 other circuits, and a controlling device for governing the passage of the current over the circuit and thereby controlling or effect-ing the operation of the switching appa-ratus. Both the switching apparatus and 75 the controlling device are preferably of substantially the construction herein illustrated and described, although either may be used without the other, providing the substituted device is capable of effecting the operation 80 of the remaining one of said mechanisms, and various changes may be made in the construction and arrangement of the parts of the switching apparatus and controlling devices as will be pointed out hereinafter. 85 This system although suitable for a small number of circuits, is particularly applicable for a large number, and I have shown the switching apparatus and the controlling devices as of suitable construction for opera-90 tion with 900 circuits, but a less number may be used therewith, and at Fig. 1 I have illustrated only three switching apparatus and a corresponding number of connected circuits. It requires however, but slight 95 changes in the construction of the switching apparatus and controlling devices to render the same capable of operation in connection with a system having a greater number of circuits than 900. 100

The separate circuits converge at a common or main station, are each provided with at least one subscriber's station and preferably consists of two line conductors or wires tical sections looking in opposite directions, which are so connected by a common conductaken respectively on lines 9—9 and 10—10, tor, cross connections, switching apparatus,

and controlling devices that a metallic circuit is established between any two connected circuits for securing substantially undis-The adjacent turbed intercommunication. ends of the line conductors or wires of the separate circuits, their main or common conductor, and the cross connections are preferably so arranged and the switching apparatus so constructed, that a movable termi-10 nal for connecting the corresponding circuit with another circuit is required to move but a minimum distance. To facilitate this result each switching apparatus is provided with a series of terminals the number of which is a submultiple, and preferably the square root, of the number of the separate circuits. Each switching apparatus is also preferably utilized to cooperate with the controlling device of the circuit connected by said switching apparatus to the circuit leading therefrom for insuring absolute secrecy between the two connected circuits. It is obvious however, that each switching apparatus may be provided with but a single 25 movable terminal and may be constructed without those features tending to secure secrecy between the connected circuits. In the operation of the switching apparatus, I also preferably avail myelf of the same line con-30 ductors or wires used for communication between the circuits, and thus reduce the expense of wiring; and when the system contains a large number of circuits, I prefer to use both conductors or wires of each circuit for effecting or controlling the operation of the respective switching apparatus. To facilitate this result the opposite ends of both of the line conductors or wires of the circuits are connected to the ground either normally or at intervals, although it is obvious, that instead of using the ground as a conductor additional wires may be substituted without material departure from this invention. As my present system is particularly applicable 45 for use with a large number of circuits some of which will necessarily be comparatively long, I prefer to actuate the switching apparatus by a suitable motor and to merely govern the movement of each switching appa-50 ratus by the corresponding controlling device; but it is apparent that instead of using a separate motor for effecting the operation of the switching apparatus, a magnet may be connected directly to each switching apparatus for producing this movement. A A<sup>1</sup>, B B<sup>1</sup>, C C<sup>1</sup>, represent suitable conductors or wires of a series of circuits, converging at a main or common station D, and provided with subscribers' stations A<sup>2</sup> B<sup>2</sup> C<sup>2</sup>; 60 a b c automatic switching apparatus at the station D connected to the adjacent ends of said conductors; and D1 a main or common conductor at the station D connected to each

of said switching apparatus and connected

source of electric energy as a dynamo D<sup>3</sup> preferably grounded by a conductor or wire D<sup>4</sup>. The subscribers' stations A<sup>2</sup> B<sup>2</sup> C<sup>2</sup> are provided with suitable telephones or other communicators A<sup>3</sup> B<sup>3</sup> C<sup>3</sup>, and signals A<sup>4</sup> B<sup>4</sup> 70 C4, which it is unnecessary to herein illustrate or describe as their construction forms no essential feature of this invention; and these telephones and the magnets of said signals are connected in circuit with con- 75 ductors or wires A5 A6, B5 B6, C5 C6, which will be referred to in describing the controlling devices. The conductors or wires A<sup>1</sup> B<sup>1</sup> C<sup>1</sup> are provided with fixed contact-terminals A<sup>7</sup> B<sup>7</sup> C<sup>7</sup> arranged preferably in 80 parallel at the main or common station D, and the switching apparatus a b c are formed with movable terminals  $a^1$   $a^2$   $a^3$ ,  $b^1$   $b^2$   $b^3$ , and  $c^1$   $e^2$   $e^3$ , which contact with said fixed terminals and are mounted on suitable sup- 85 ports a4 b4 c4, forming parts of the respective switching apparatus a b c. The fixed contact-terminals preferably extend longitudinally across the paths of all of the movable terminals of the switching apparatus, 90 but it is obvious that each circuit may be provided with a separate fixed terminal for each switching apparatus. Said fixed contact-terminals A<sup>7</sup> B<sup>7</sup> C<sup>7</sup> may consist of separated wires or, as illustrated, of compara- 95 tively thin bars separated by suitable insulation d.

Suitable cross conductors A<sup>8</sup> B<sup>8</sup> C<sup>8</sup> extend from the fixed contact-terminals  $A^{\tau}$   $B^{\tau}$   $C^{\tau}$ and may connect directly to their respective 10 circuit conductors A<sup>1</sup> B<sup>1</sup> C<sup>1</sup>, although in order to aid in insuring secrecy when two circuits are connected, these cross conductors A<sup>8</sup> B<sup>8</sup> C<sup>8</sup> terminate at circuit breakers A<sup>9</sup> B<sup>9</sup> C9 which are connected by conductors or 10 wires A<sup>10</sup> B<sup>10</sup> C<sup>10</sup> to said circuit conductors A<sup>1</sup> B<sup>1</sup> C<sup>1</sup> and are operated by the respective switching apparatus, a b c, as presently described. Each switching apparatus is here shown as provided with a plurality of mov- 11 able terminals, and consequently each movable terminal engages only a limited number of the fixed contact-terminals, and if desired the first terminal of the series engaged by one of the movable terminals may be slightly 11 separated from the last terminal of the series engaged by the next adjacent movable terminal, as illustrated at Figs. 2 and 3, although this arrangement is not essential.

The number of the movable terminals of 12 each switching apparatus preferably equals the square root of the number of the circuits of the system, but the number of said movable terminals may be either greater or less than said square root although it should be 12 a submultiple of the total number of said circuits. The switching apparatus here illustrated being designed for use with 900 electric circuits, is therefore preferably pro-65 by a conductor or wire D2 to a suitable vided with 30 movable terminals, and the 13

fixed contact-terminals of the circuits are side of the support at and is movable indeit necessary or advisable to illustrate either trolled by an electrically operated mechathe entire number of fixed contact-terminals, nism connected to the circuit leading to the 70 or a terminal support provided with 30 movable terminals, but at Fig. 2 I have shown two entire series of 30 fixed contact-terminals and two movable terminals  $a^2$   $a^3$  of 10 the switching apparatus as presently described, suitably separated from each other for engaging the fixed terminals of each of said series. The remaining fixed and movable terminals of my electric ex-change system are arranged similar to the like terminals previously referred to, and the terminal support of each switching apparatus is required to move only as far as any one of its movable terminals. It is ob-20 vious however that if the switching apparatus are each provided with a greater or less number of movable terminals, that their terminal supports will be required to move a less or greater distance.

The switching apparatus of my exchange system are all of the same construction and in order to simplify the description of this invention I will specifically describe only the one a. The terminal support  $a^4$  of said 30 apparatus a preferably consists of a reciprocating insulating bar or strip formed with cutouts  $a^5$  for receiving the movable terminals  $a^1$   $a^2$   $a^3$ , &c., which are electrically connected by a suitable conductor as a bar or 35 strip a<sup>6</sup>, secured to said support a<sup>4</sup> and connected to the movable conductor A<sup>10</sup>. It is desirable that the terminals  $a^1 a^2 a^3$  may move independently, and they are therefore preferably secured to the conductor a6 by conduct-40 ing pivots  $a^7$  and are normally held out of operative position against the action of springs  $a^8$  arranged in the cutouts  $a^5$ . The means for holding the movable terminals out of operative position preferably consists of pins or rods  $\alpha^9$ , moved lengthwise in apertures or guides in the support  $a^4$ , by a reciprocating rack  $a^{10}$ , presently described, which is provided with cutouts  $a^{11}$  arranged one in advance of the other for permitting the 50 springs  $a^8$  to successively force said pins or rods into inoperative position and to successively force the movable terminals  $a^1$   $a^2$   $a^3$ into their plane of engagement with the fixed terminals  $A^{\tau}$   $B^{\tau}$   $C^{\tau}$ . The pins or rods 55  $a^9$  preferably engage the movable terminals  $a^1$   $a^2$   $a^3$ , but electrical connection between said parts is prevented by insulators  $a^{12}$ . The movable terminals  $a^1$   $a^2$   $a^3$  are however, electrically connected to the conductor or 60 wire  $A^{10}$  by the conductor  $a^6$  fixed to the support a4, and said conductor A10 which

is preferably flexible is free to move when the support  $a^4$  is advanced to the desired position as presently described.

The rack  $a^{10}$  is preferably arranged at one spring  $a^{22}$ .

divided into 30 series each containing the pendently thereof in the direction indicated terminals of 30 circuits. I have not deemed by arrow 1, Fig. 3, by a suitable feed conswitching apparatus a and composed of the line conductors or wires A A<sup>1</sup>. The terminal support  $a^4$ , and the rack  $a^{10}$  may be suitably guided in their movement, but the terminal support  $a^4$  is shown as interposed between 75 the rack  $a^{10}$  and a supporting plate or bar d, preferably formed of insulating material and arranged in substantially the same plane as the engaging faces of the fixed contact-terminals  $A^7$   $B^7$   $C^7$ . The rack  $a^{10}$  is inter- 80 posed between the terminal support  $a^4$  and cross bars  $d^1$   $d^2$  arranged at the outside of said rack, and said cross bars may be provided with guides  $d^3$   $d^4$  for preventing transverse movement of the rack ato. The sup- 85 port  $a^4$  is provided with projecting arms  $\tilde{a}^{13}$ which engage the opposite faces of the rack a<sup>10</sup> and prevent lateral movement of said support, and if desired, a tongue and groove connection between the adjacent edges of 90 said support and rack, or suitable guide pieces or bars, not necessary to herein illustrate, may be used to prevent a lateral movement of the support  $a^{\bullet}$ .

The feed for the rack  $a^{10}$  may be of any 95 desirable construction but it preferably consists of a feeding dog  $a^{14}$ , a suitable stop as a dog  $a^{15}$ , a motor  $D^5$  and suitable connections between the feeding dog and the motor. The feeding dog  $a^{14}$  is arranged at the 100 outside of the rack  $a^{10}$  and is pivoted at  $a^{16}$ to a suitable support  $a^{17}$  which may be provided with ears  $a^{18}$  for guiding the rack  $a^{10}$ , and is mounted on the main conductor or common conductor  $D^1$  consisting preferably 105 of a spindle or pivotal pin. A spring  $a^{19}$ normally forces the free end of the feeding dog toward the rack  $a^{10}$ , but a pin  $a^{20}$ secured to the support  $a^{17}$  and movable in a slot  $a^{21}$  in the feeding dog, normally prevents the engagement of said dog and rack. The pin  $a^{20}$  and the slot  $a^{21}$  connect the feeding dog to the support  $a^{17}$  with a lost motion at a point between the pivot  $a^{16}$  and the free end of the dog, and this connection 115 enables the feeding dog to swing on its pivot when engaged with the rack  $a^{10}$ , until the pin  $a^{20}$  reaches the opposite end of the slot  $a^{21}$ , whereupon the support  $a^{17}$  holds said dog firmly in engagement with the 120 rack and prevents undue feeding thereof. The support  $a^{17}$  is reciprocated to and fro, as presently described, and each forward movement operates the dog  $a^{14}$  to feed the rack  $a^{10}$  a single tooth or step. The stop or  $^{125}$ dog  $a^{15}$  prevents return movement of the rack  $a^{10}$  and is preferably mounted on the conductor or spindle D1 and normally engaged with the rack  $a^{10}$  by a suitable

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The motor D<sup>5</sup> for operating the feed for the rack a10 may be of any desired form, size, and construction, and the support  $a^{17}$  may be suitably connected thereto. In the prefit terms of my invention, the motor  $D^5$ consists of a constantly oscillating shaft which is provided with a lengthwise shoulder  $d^5$ , and is actuated by any suitable mechanism not necessary to herein illustrate or 10 describe. The connection between said motor and the support  $a^{17}$  preferably consists of a movable arm  $a^{23}$  having one end pivoted at  $a^{24}$  to the outer end of the support  $a^{17}$ and its opposite end movable into engage-15 ment with the shoulder  $d^5$ . As the arm  $a^{23}$ is engaged with the shoulder  $d^5$ , as presently described, the support  $a^{17}$  is rocked on the conductor or spindle  $D^1$  in the direction shown by arrow 2, Figs. 2 and 3, against the 20 action of a spring  $a^{25}$  and operates the feeding dog  $a^{14}$  to advance the rack  $a^{10}$  a single tooth. The spring  $a^{25}$  then operates to return the support  $a^{17}$  and gravity is utilized to facilitate said movement and to hold the 25 arm  $a^{23}$  in its normal position, since I preferably arrange the terminal support at and the rack  $a^{10}$  in a vertical plane. It is obvious however that if the parts  $a^4$   $a^{10}$  are otherwise arranged, a suitable spring may be 30 utilized to return the arm  $a^{28}$ .

The electrically operated mechanism for connecting the feeding dog support with the motor D<sup>5</sup> may be of any desirable form, size, and construction, but it preferably con-35 sists of a magnet  $a^{26}$  in circuit with the conductor or wire A, and a lever  $a^{27}$  pivoted to a suitable support  $a^{28}$  and having one end connected by a link  $a^{29}$  to the armature of said magnet and its opposite end engaged 40 with the movable arm a<sup>23</sup>, for forcing the same into engagement with the shoulder  $d^5$  of the motor  $D^5$ . As will be presently described, the passage of the current through the magnet  $\hat{a}^{26}$  is governed by a suitable con-45 trolling device e, but in order that the operation of the switching apparatus may be positively assured, a suitable circuit breaker is connected to the line conductor or wire A in proximity to the switching apparatus a 50 for breaking the circuit through said conductor at each movement of the rack  $a^{10}$ , and the break in said circuit is utilized to advance the operating pieces of the controlling device, presently described, which regulate the operation of said controlling device. Any suitable circuit breaker may be used for this purpose, and I have here illustrated one of simple construction consisting of a terminal  $a^{30}$  connected to a wire  $a^{31}$ 60 leading from the magnet  $a^{26}$  and detachably engaged with the upper end of the feeding dog support  $a^{17}$ , which is formed of electric conducting material and permits the passage of the current from the terminal  $a^{80}$  to the

65 main or common conductor D1.

As the feeding dog support  $a^{17}$  is moved onwardly from its normal position for advancing the rack  $a^{10}$  a single step, the upper end of said support is separated from the terminal  $a^{30}$  and the circuit through the line 70 conductor or wire A is thus broken until said support assumes its normal position in engagement with the terminal  $a^{30}$ ; whereupon a current may be again passed through the line conductor or wire A for engaging 75 the arm  $a^{23}$  with the motor D<sup>5</sup> and thereby effecting a second advance movement of the rack  $a^{16}$ . Consequently, as the break in the circuit through the conductor or wire A, is dependent upon each movement of the rack 80  $a^{10}$  and the movement of the operating pieces of the controlling device e, presently described, which regulate the operation of said controlling device is dependent upon each break of the circuit through the conductor or 85 wire A, it is obvious that the magnet  $a^{26}$  remains energized for connecting the feeding dog support with the motor D<sup>5</sup> until said parts are connected and the feeding dog support commences its onward movement. 96 Moreover, no additional current pulsation is passed through the conductor or wire A for operating the switching apparatus a until the support  $a^{17}$  is in its normal position and again restores the circuit through the 95 line conductor or wire A.

The rack  $a^{10}$  is moved lengthwise as described until the desired-movable terminal of the corresponding support  $a^4$  has been forced into operative position, whereupon the rack 100 is connected by any suitable mechanism to said support  $a^4$  for moving the same lengthwise until said movable terminal engages the desired fixed contact-terminal. Said connecting mechanism preferably consists of a 105 magnet  $a^{32}$  connected in circuit with the line conductor or wire  $A^1$ , a connecting dog  $a^{33}$  pivoted to one or both of the ears  $a^{13}$  of the support  $a^4$  and movable into engagement with the rack  $a^{10}$ , and a stop or dog  $a^{34}$  for 110 normally holding the connecting dog out of operative position.

operative position. The magnet  $a^{32}$  may be connected to the grounded main conductor D' by any suitable means, but I have here shown said magnet 115 as connected thereto by a wire  $a^{35}$ , the feeding dog support  $a^{17}$ , and conducting springs  $a^{36}$   $a^{37}$   $a^{38}$  interposed between said wire and support. The wire  $a^{35}$  is suitably connected to the spring  $a^{36}$ , which is normally engaged 120 with the spring  $a^{37}$ . The spring  $a^{38}$  is suitably secured to the spring  $a^{37}$  and its free end is engaged by the outer end of the feeding dog support  $a^{17}$ , when in its advance position as seen at Fig. 3. The spring  $a^{36}$  125 tends to move outwardly from engagement with the spring  $a^{37}$ , Fig. 3, but is normally held in position for engaging said spring  $a^{37}$  by one of the arms  $a^{13}$  of the terminal support  $a^{4}$ . Upon the first onward movement 130

of the terminal support  $a^4$  the spring  $a^{36}$  a with the nine hundredth circuit. This and the circuit through the line conductor or wire A<sup>1</sup> to the conductor D<sup>1</sup> is broken 5 and is not again established until the return of said support to its normal position, as presently described. A spring  $a^{30}$  is utilized to force the connecting dog  $a^{23}$  into engagement with the rack  $a^{10}$ , and a link  $a^{40}$  of 10 considerable length is interposed between the stop dog  $a^{34}$  and the armature of the magnet  $a^{32}$ . As the magnet  $a^{32}$  is energized, the stop or dog  $a^{34}$  is withdrawn from operative position and the connecting dog  $a^{33}$  is ative position and the connecting dog  $a^{33}$  is 15 engaged with the rack  $a^{10}$  by the spring  $a^{39}$ , whereupon the support a4 is fed to the desired position by said rack. During this movement of the support  $a^4$ , the stop or dog a34 is held outwardly on its pivot for pre-20 venting stoppage of the support by the  $link a^{40}$ 

As previously described, the rack  $a^{10}$  permits the movable terminals to assume their operative position, is connected to the support  $a^4$  as soon as the desired movable terminal is in operative position, and moves the support  $a^4$  from its normal position until said movable terminal is in engagement with the desired fixed contact-terminal. The 30 terminal support  $a^{*}$ , as previously stated, is provided with thirty movable terminals, which are so arranged that when one first assumes operative position it is separated one step from the first terminal of the ad-35 jacent series of fixed contact-terminals. Consequently, to engage the first movable terminal  $a^1$  of the support  $a^4$  with the first one of the adjacent series of fixed contactterminals, it requires one movement of the 40 feed for the rack  $a^{10}$  to permit the terminal  $a^1$  to assume its operative position and a second movement of said feed to engage the terminal  $a^1$  with said fixed contact-terminal. It, therefore, requires sixty movements of 45 said feed to engage the last movable terminal not illustrated of the support  $a^4$  with the last fixed contact-terminal engaged thereby, and to thus connect the circuit leading from the switching apparatus a to the nine 50 hundredth circuit of the system.

After two circuits have been connected by the switching apparatus a, it is desirable for the switching apparatus to again assume its normal position, and this result may be 55 effected by any suitable mechanism. The switching apparatus a and the corresponding controlling device e are, however, preferably of such construction, that after the desired communication through said connected cir-60 cuits has been secured, the controlling device e operates to permit the passage of electric current pulsations through the magnet  $a^{26}$  until the rack  $a^{10}$  has passed beyond its position assumed when connecting the cir-65 cuit leading from the switching apparatus cator of an additional circuit seeking con- 130

moves outwardly to its inoperative position, additional movement of the rack  $a^{10}$  which preferably consists of two advances or steps is utilized to effect automatic return of said rack and the support at to their normal posi-70 tion. To permit of this result a shoulder  $a^{41}$ secured to said rack, and thus connected to the terminal support  $a^4$ , engages an operating piece  $a^{42}$  of suitable construction for forcing the stop  $a^{15}$  from operative position. The 75 automatic return by gravity of the support and rack  $a^4$   $a^{10}$  is thus permitted and may be accelerated by weighting said parts. The operating piece a42 is of suitable construction, but preferably consists of a reciprocat- 80 ing bar guided in the cross bar  $d^2$  and having one end provided with a shoulder arranged in the path of the shoulder  $a^{41}$ , and its opposite end provided with a cam face  $a^{43}$  for engaging an arm upon the stop  $a^{15}$  85 and rocking said stop on the conductor or spindle  $D^1$  until its engaging end is with-drawn from the rack  $a^{10}$ . The operating piece also preferably holds the stop  $a^{15}$  out of operative position and is therefore pro- 90 vided with a notch a44 for receiving a corresponding tooth provided upon said stop. As the rack  $a^{10}$  assumes its normal position, a suitable shoulder  $a^{45}$  thereon forces the operating piece  $a^{42}$  out of operative position 95 and the stop  $a^{15}$  is again engaged with said rack by the spring  $a^{22}$ . When rack  $a^{10}$ reaches the normal, its upper shoulder causes dog  $a^{33}$  to disengage the teeth of rack  $a^{10}$  and to be held disengaged by locking dog  $a^{34}$ . 100 Support  $a^4$  is thus unlocked from rack  $a^{10}$ .

It is very desirable to secure secret communication between two connected circuits and although this result may be effected by various means, I preferably utilize for its 105 accomplishment the switching apparatus of one of said circuits and the controlling device of the other. When a switching apparatus connects its corresponding circuit withanother, the terminal support of said switch- 110 ing apparatus is moved away from its normal position and breaks the circuit from its fixed contact-terminal. The current for connecting two circuits must be passed through the fixed terminal of the called sta-115 tion and thence through the line conductor or wire normally connected thereto, and when the circuit from the fixed contact-terminal of a station is broken, it is impossible 120

to connect with said circuit. As will be apparent after the description of the operation of the controlling devices

of my electric exchange system, the terminal support of the controlling device of a connected or called circuit is forced from its 125 normal position when the circuits are connected for telephonic or other communication, and thus prevents the operative con-nection of the telephone or other communi-

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ing to the like parts  $a^1$   $a^2$   $a^3$   $a^4$   $a^{10}$   $a^{14}$   $a^{15}$ ,  $a^{17}$ , obvious that secret communication between two circuits is effected by the switching apparatus of one and the controlling device of 5 the other, and that an additional circuit cannot be connected for intercommunication with either of said connected circuits.

The switching apparatus of the respective circuits of my system preferably operate in 10 connection with suitable circuit breakers for aiding in securing the desired secrecy of communication, and, as I have here illustrated but three switching apparatus a b c, I have shown but three of the circuit break-15 ers A<sup>9</sup> B<sup>9</sup> C<sup>9</sup>, previously mentioned. In order that the construction of said circuit breakers and the operation of the respective switching apparatus necessary for actuating the circuit breakers may be readily appar-20 ent, I will now proceed to describe the circuit breaker connected to the switching apparatus a. This circuit breaker A<sup>9</sup> may be of any desirable form, size, and construction, but it preferably consists of a contact 25 piece secured to one end of the cross conductor A<sup>8</sup> and normally contacted with the conductor  $a^6$  which is electrically connected to the movable conductor  $A^{10}$ . Consequently, when the support  $a^4$  is in its nor-30 mal position the conductors  $A^8$   $A^{10}$  are connected by said circuit breaker and the current is free to pass from the cross conductor A<sup>8</sup> over the conductor A<sup>10</sup> to the line

conductor or wire A1. As soon as the support  $a^4$  moves from its normal position for connecting one of its movable terminals with the fixed contact-terminal of another circuit, the conductor  $a^6$  is disconnected from the circuit breaker A<sup>9</sup> and the circuit from

40 the fixed contact-terminal  $A^7$  through the cross conductor or wire  $A^8$  to the line conductor A1 is broken, and, even though a circuit should be connected with said fixed contact-terminal, it would be cut off from com-

45 munication with the line conductor or wire may be utilized for effecting contact of said 110 A<sup>1</sup>. As previously stated the controlling device of the called circuit operates to prevent the connection of any additional circuit thereto, but as the detail construction and

50 arrangement of the parts of the controlling devices of my system have not yet been described, the operation of the controlling device for effecting this result will be subsequently pointed out.

As previously stated, the switching apparatus b c are of the same construction as the apparatus a, and at Fig. 1 I have diagram-

 $a^{23}$   $a^{26}$   $a^{32}$ ,  $a^{27}$   $a^{29}$   $a^{40}$   $a^{30}$   $a^{36}$   $a^{33}$   $a^{34}$ ,  $a^{42}$ ,  $A^{9}$  of

the switching apparatus a.

The switching apparatus a b c are arranged side by side and the motor D<sup>5</sup> pref- 70 erably extends crosswise thereof as seen by dotted lines at Fig. 1, in order that it may operate all of said apparatus. The conductor D¹ also preferably extends crosswise of the switching apparatus a b c and forms 75 both a main or common electric conductor therefor, and a support or spindle for the feeding and stop dogs of their respective feed mechanisms. It is obvious however that a separate motor may be used for each 80 switching apparatus and that any other suitable main or common conductor may be utilized for connecting said switching apparatus.

The circuits leading from the stations  $A^2$ B<sup>2</sup> C<sup>2</sup> are provided with controlling devices efg which are all of the same construction, and, in order to additionally simplify the description of this invention, I will describe only the controlling device e for the circuit 90 leading from the station  $A^2$ . This controlling device consists of a suitable supporting frame  $e^1$ , a series of fixed brushes or terminals  $e^2$   $e^3$   $e^4$   $e^5$   $e^6$ , a movable terminal support e7, movable operating pieces e8 e9 for 95 automatically operating the terminal support  $e^{\tau}$ , escapements for controlling the movement of said terminal support and operating pieces, and an actuating piece  $e^{10}$  for

moving the terminal support.

The fixed brushes or terminals  $e^2$   $e^3$   $e^4$   $e^5$   $e^6$ are of suitable form, size, and construction, are preferably arranged one alongside of the other and are secured to any desirable support  $e^{11}$  projecting from the rear wall of the 105 frame  $e^{1}$ . The terminal support  $e^{7}$  is provided with suitable terminals  $e^{12}$   $e^{13}$   $e^{14}$   $e^{15}$  $e^{16}$   $e^{17}$   $e^{18}$  for engaging the former terminals e2 e3 e4 e5 e6, and in order that rotary motion terminals, the support  $e^7$  preferably consists of a drum mounted on a spindle  $e^{10}$  connected to a suitable grounded conductor or wire  $e^{20}$ . The terminals  $e^{12} e^{13} e^{14} e^{17}$  are electrically connected to the spindle  $e^{19}$  in 115 any suitable manner, as by contact, and the terminals e15 e16 e18, which may be designated as surface terminals, are insulated from said spindle.

The controlling device e when suitably 120 adjusted preferably operates automatically for making connection with a desired circuit apparatus a, and at Fig. 1 I have diagrammatically shown movable terminals  $b^1$   $b^2$   $b^3$ ,  $c^1$   $c^2$   $c^3$ , terminal supports  $b^4$   $c^4$ , racks  $b^{10}$   $c^{10}$ , stops or dogs  $b^{15}$   $c^{15}$ , ment of the terminals  $e^2$   $e^3$   $e^4$   $e^5$   $e^6$ ,  $e^{12}$   $e^{14}$  125 supports  $b^{17}$   $c^{17}$ , arms  $b^{23}$   $c^{23}$ , magnets  $b^{26}$   $b^{32}$ ,  $c^{26}$   $c^{32}$ , levers  $b^{27}$   $c^{27}$ , links  $b^{20}$   $b^{40}$ ,  $c^{29}$   $c^{40}$ , terminals  $b^{30}$   $b^{36}$ ,  $c^{30}$   $c^{36}$ , connecting dogs  $b^{36}$ ,  $c^{30}$   $c^{36}$ , operating pieces  $b^{33}$   $c^{33}$ , stop dogs  $b^{34}$   $c^{34}$ , operating pieces  $b^{32}$   $c^{42}$  and circuit breakers  $b^{6}$   $b^{6}$  corresponding this operation with a desired circuit and during this operation the terminal support  $e^7$  is revolved for varying the engage, port  $e^7$   $e^{16}$   $e^{17}$   $e^{18}$ . The mechanism for revolving the support  $e^7$  may be of any suitable form, size, and construction, although it preferably consists of a spring, an escapement for permitting the operation of the spring, and 130

operating pieces  $e^8$   $e^9$ , an actuating piece  $e^{10}$ and a magnet e21 for operating the escapement. As clearly seen at Fig. 1, the line conductors or wires A1 A terminate at the fixed brushes or terminals  $e^2$   $e^6$ ; the conductors  $A^5$   $A^6$ , previously mentioned, respectively connect the brushes or terminals  $e^5$   $e^3$  to the lie conductor  $A^1$  and the terminal  $e^2$ ; and a conductor or wire  $e^{22}$  connects the brush 10 or terminal e<sup>4</sup> to the line conductor A. previously stated, the telephones or other communicators A<sup>2</sup> and the magnets of the signals A4 are connected in circuit with the conductors or wires  $A^5$   $A^6$ , and a second 15 magnet  $e^{23}$  and the magnet  $e^{21}$  are respectively connected in circuit with the conductors or wires A A<sup>6</sup> for controlling the escapements which govern the advance movement of the operating pieces  $e^8$   $e^9$  and the ter-20 minal support  $e^7$ . The magnet  $e^{21}$  may be formed of wire of high resistance as German silver, for reducing the amperage of the current passed through the conductor or wire A<sup>6</sup> when the signals of two connected 25 circuits are operated, but I preferably use

This resistance  $e^{24}$  usually consists of an electric lamp which is arranged in proximity to the telephone or other communicator  $A^3$ , and is particularly useful for guiding a subscriber to said telephone when darkness obscures its locality.

for such purpose a separate resistance  $e^{24}$ 

connected in circuit with the conductor A<sup>6</sup>.

The terminal support  $e^{\tau}$  is preferably so 35 arranged when in its normal or initial position that the terminals e12 e3 are in contact, and a current for operating the signal A4 is thus free to pass from a calling circuit over the conductors or wires  $A^1$   $A^6$  to the grounded wire  $e^{20}$ , and in its passage illuminates the electric lamp  $e^{24}$  and energizes the magnet of the signal  $A^4$ . Said current also energizes the magnet  $e^{21}$  and tends to move its armature which is connected to operate 45 the escapement for the terminal support  $e^{\tau}$ , but as will be afterward explained, the armature of the magnet  $e^{21}$  is prevented from movement at this time and cannot operate said escapement. The telephone or other communicator A<sup>3</sup> is arranged in close proximity to the controlling device e and normally restrains the actuating piece  $e^{10}$ , presently described, from operative position. When the signal A<sup>4</sup> is operated as described, 55 by a calling circuit, the subscriber removes the telephone  $A^3$  from its normal position and the actuating piece  $e^{10}$  reversely rotates the terminal support  $e^{\tau}$  until the surface terminals  $e^{18}$  engages the fixed brushes or ter-60 minals  $e^4$   $e^5$  and connects the telephone A<sup>3</sup> in metallic circuit with the line conductors A A<sup>1</sup>. This reverse movement of the terminal support  $e^{\tau}$  breaks the normally grounded circuit through the terminals  $e^3$ 65  $e^{12}$  and the conductor  $e^{20}$ , and, as presently

described, thereby controls the connection of the telephone to the line conductors or wires

of the calling circuit.

When the controlling device e is utilized to operate the switching apparatus a for 70 connecting another circuit with the conductors A A<sup>1</sup>, the operating pieces  $e^{8}$   $e^{9}$ , are first placed in the desired position, and a suitable spring for actuating the operating pieces is tensioned. as presently described. The ter- 75 minal support  $e^{\tau}$  is then permitted to make its first advance or step in the direction indicated by arrows 3, Figs. 1, 9, 12, for separating the terminals  $e^{i2}$   $e^{3}$  and engaging the terminals  $e^{13}$   $e^{6}$ , thus disconnecting the 80 ground from the line conductor  $A^{1}$  and connecting the same to the line conductor A which is provided with the magnet  $e^{23}$  previously mentioned. The controlling device ethen operates automatically to effect onward 85 movement of the rack  $a^{io}$  of the switching apparatus a, for permitting the desired movable terminal of said apparatus to assume its operative position, as previously described; and upon each advance of said 90 rack, the circuit through the conductor A is broken and the armature of the magnet  $e^{23}$ is actuated to permit the advance of the operating pieces  $e^{8}$   $e^{9}$ . The movement of the rack  $a^{10}$  and the operating pieces  $e^{8}$   $e^{9}$  con- 95 tinues until the operating piece e<sup>8</sup> reaches its operative position whereupon it permits a second advance or step of the terminal support  $e^{\tau}$  for connecting the terminals  $e^{14}$   $e^2$ and thereby grounding the line conductor  $A^1$ . 100 This second advance movement of the terminal support  $e^{\tau}$  is, however, not sufficient to disconnect the terminals  $e^{13}$   $e^{6}$  and thus break the ground connection for the line conductor  $\overline{\mathbf{A}}$ , as the terminal  $e^{13}$  is of con- 105 siderable length.

Immediately after the second advance or step of the support  $e^{\tau}$ , the feeding dog support a<sup>17</sup> engages the terminal a<sup>38</sup> and a current is free to pass from the main station D 710 through the line conductor A<sup>1</sup> for connecting the rack a10 of the switching apparatus  $\alpha$  to the terminal support  $\alpha^4$  as previously described. The controlling device e then continues to advance the rack  $a^{10}$  after its 115 connection to the support  $a^4$ , until the operating piece  $e^9$  permits the support  $e^7$  to make a third advance or step for disconnecting the terminals  $e^{13}$   $e^{6}$ ,  $e^{14}$   $e^{2}$  and connecting the terminals  $e^{15}$ ,  $e^{3}$   $e^{4}$ . The signal  $A^{4}$  is then 120 connected in circuit with the line conductors, the current passing from conductor A through conductor  $e^{22}$  fixed terminal  $e^4$  movable terminal  $e^{15}$  of the support  $e^7$ , fixed terminal  $e^3$  conductor  $A^6$  to the conductor  $A^1$ , 125 and the current from the main station D passes from the line conductor A through the controlling device e and the line conductor  $A^{1}$  to the movable terminal of the switching apparatus a in operative position, 130

and thence through the fixed contact-terminal A7 of the connected or called circuit and the normally grounded line conductor leading from said contact-terminal as will 5 be hereinafter described. In its passage through said line conductors, the current energizes the magnet  $e^{21}$ , operates the signal A<sup>4</sup>, and energizes and operates the corresponding magnet and signal of the connected 10 circuit.

Upon the operation of the signal of the called circuit the subscriber of said circuit removes his telephone or other communicator from its normal position, whereupon 15 the terminal support of the adjacent controlling device is reversely moved for connecting said telephone to both of the corresponding line conductors or wires and breaking the ground from said controlling device. The signals of the connected cir-20 device. cuits then cease their operation and the magnet  $e^{21}$  is deenergized whereupon the terminal support  $e^{\tau}$  is permitted to make a fourth advance or step for engaging the 25 terminals  $e^{16}$   $e^4$   $e^5$  and connecting the telephone A<sup>3</sup> in circuit with the line conductors A A<sup>1</sup>. The subscribers of the connected circuits are then free to communicate with each other over a metallic circuit composed of 30 the line conductors or wires of both circuits, since their corresponding conductors are connected at the main station by the common or main conductor D1 and the switching apparatus a.

After the desired communication has been obtained, the telephones or other communicators of the connected circuits are again returned to their normal position, thereby causing the reversely moved terminal sup-40 port of the called circuit to assume its normal position and permitting a fifth advance or step of the support  $e^{\tau}$  for connecting the terminals  $e^{1\tau}$   $e^6$ . The circuit from the main station D is then free to pass through the 45 line conductor A to the grounded conductor

 $e^{20}$ , and consequently the rack  $a^{10}$  and the operating pieces  $e^8$   $e^9$  continue to advance until the limit of their movement is reached. The last advance movement of the rack  $a^{10}$ 50 is utilized to return said rack and the terminal support at to their normal position and, during the corresponding movement of the operating pieces  $e^8$   $e^9$ , a third operating piece  $e^{25}$  permits the sixth and last advance

55 or step of the terminal support  $e^7$ , for separating the terminals  $e^{17}$   $e^6$  and engaging the terminals  $e^{12}$   $e^3$ . The engagement of the terminals  $e^2$   $e^3$   $e^4$   $e^5$   $e^6$ ,  $e^{12}$   $e^{13}$   $e^{14}$   $e^{15}$   $e^{16}$   $e^{17}$   $e^{18}$ 

60 the main station D through the line conductors or wires A A1 for operating the switching apparatus a and the controlling preventing onward movement of the sup-

automatic mechanism is utilized for effecting their engagement and obviating the liability of any mistake incidental to hand operation. Said terminals may be suitably constructed however to permit of their de- 70 sired engagement by hand, and indeed in some instances, the terminals  $e^2$   $e^6$   $e^{13}$   $e^{14}$   $e^{17}$ will be unnecessary. I may also prefer to operate the signals of two connected circuits by some other current than the one passing 75 from the main station D through both line conductors of the calling circuit and the normally grounded line conductor of the called circuit, and in that event, the terminal  $e^{15}$  may be dispensed with. It is also obvious 80 that providing these changes are made in the switching apparatus a and the terminals of the controlling device e, it may be advisable to somewhat vary the arrangement and engagement of the remaining terminals of 85 said controlling device. Moreover, the magnets  $e^{21}$   $e^{23}$  may be connected to the terminal support  $e^7$  and the operating pieces  $e^8$   $e^9$ , so as to directly effect the movement of said parts instead of operating escapements to 90 permit suitable springs to accomplish this

As previously outlined, a rotary drum or terminal support, operating pieces, magnets, an actuating piece, and escapements are uti- 95 lized to effect the desired engagement of the terminals of the controlling device e, and although said parts may be of any suitable form, size, and construction, and may be connected in any desired manner, I will now 100 proceed to briefly describe their preferable construction and connections. The drum  $e^{\tau}$ is loosely mounted on the spindle  $e^{19}$  and is revolved thereon by a spiral spring  $e^{26}$  having its opposite ends secured to said drum 105 and spindle, Fig. 15. One end of the spindle  $e^{19}$  is journaled in the rear wall of the supporting frame  $e^1$ , and its opposite end in a gear  $e^{27}$  having its hub journaled in the supporting wall  $e^{28}$  of the frame e.

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The drum  $e^{\tau}$  is normally restrained from movement by its escapement which preferably consists of a toothed wheel  $e^{29}$ , holdings dogs  $e^{30}$   $e^{31}$ , and rocking arms  $e^{32}$  for actuating said dogs. The wheel  $e^{29}$  is pref- 115 erably fixed to the drum  $e^7$ ; the dogs  $e^{30}$   $e^{31}$ are mounted on a suitable pivot  $e^{33}$ , and the arms  $e^{32}$  are fixed to a rocking shaft  $e^{34}$  provided with an arm  $e^{35}$ . One of the arms  $e^{32}$ is preferably utilized as the armature for 120 the magnet  $e^{21}$  previously referred to, and a suitable spring  $e^{36}$  normally separates said armature arm  $e^{32}$  from the pole pieces of the thus controls the passage of currents from magnet  $e^{2i}$ , thereby permitting the main the main station D through the line conescapement dog  $e^{30}$  to rock into engagement 128 with the adjacent tooth of the wheel  $e^{29}$  for device e.

The terminals  $e^{12}$   $e^{13}$   $e^{14}$   $e^{15}$   $e^{16}$   $e^{17}$   $e^{18}$  are ment dog  $e^{31}$  out of engagement with said wheel  $e^{29}$ . The arms  $e^{32}$  are rocked from 130

their normal position by the lever which tensions the main driving spring of the controlling device e, the operating pieces  $e^8$   $e^9$   $e^{25}$ , and the magnet  $e^{21}$ , and are returned to their normal position by the spring  $e^{36}$ When the arms  $e^{32}$  are moved against the action of the spring e36, the main escapement dog  $e^{30}$  is forced out of operative position and the secondary escapement dog  $e^{31}$  10 permits a slight onward movement of the drum  $e^{\tau}$  and then prevents its further movement. As the spring  $e^{36}$  returns the arms  $e^{32}$ . the dog  $e^{s_1}$  is withdrawn from operative position and the support  $e^{\tau}$  continues the bal-15 ance of its onward advance or step, until the dog e30 engages the tooth next adjacent to

that previously engaged thereby. The operating pieces  $e^8$   $e^9$  Figs. 13 and 14 may be of any desirable form, size, and con-20 struction, and are capable of assuming a number of different positions in which they are securely held by any suitable means as a support or disk  $e^{37}$  which rotates said operating pieces and engages the same with 25 the arm  $e^{35}$  for rocking the shaft  $e^{34}$  and the arms  $e^{32}$  and thereby operating the escapement for the drum  $e^{7}$  to permit the second and third advances or steps thereof. Said operating pieces are preferably secured to 30 indicators or hands  $e^{38}$   $e^{39}$  which facilitate their adjustment and are preferably pivoted upon the outer end of the spinde  $e^{19}$ . The free ends of the indicators or hands  $e^{38}$   $e^{39}$  are provided with suitable bearings  $e^{40}$  in 35 which the operating pieces  $e^8$   $e^9$  are reciprocally movable, and the support or disk  $e^{37}$ is preferably formed with a series of apertures  $e^{41}$  for receiving the inner ends of said operating pieces. The apertures  $e^{41}$  are pref-40 erably arranged in a circular series and as the controlling device e is designed for use with a rack a capable of making 62 steps I preferably use 61 apertures. The operating pieces  $e^8$   $e^9$  are free to enter 60 of these 45 apertures and thus assume 60 different positions but one of the apertures is preferably closed by the operating piece  $e^{25}$ . It is obvious however, that if the 1st and 60th apertures are suitably separated and the operating piece  $e^{25}$  is interposed between the same, the 61st aperture may be dispensed with and the operating piece  $e^{25}$  otherwise secured to the support or disk  $e^{37}$ . In order that the operating pieces  $e^8$   $e^9$  may be readily placed 55 in the desired position the front wall of the frame  $e^1$  is provided with a suitable indicator  $e^{42}$  consisting of graduations normally

alined with the apertures  $e^{41}$  and when the indicators or hands  $e^{38}$   $e^{39}$  are directly alined 60 with two of said graduations the operating pieces e<sup>8</sup> e<sup>9</sup> are free to enter the corresponding apertures  $e^{41}$  and are in the desired position for effecting the movement of the terminal support  $e^{\tau}$  necessary to connect the de-

65 sired circuit to the conductors A A1.

In order to utilize the controlling device e for actuating the switching apparatus a to connect any desired circuit with the line conductors A  $A^1$  it is necessary to place both of the operating pieces  $e^8$   $e^9$  in their designed 70 position and consequently each circuit of my exchange system is designated by a combination indicator, which may consist of two separate indicators composed of numerals, letters or other characters arranged in suit- 75 able combination for permitting the desired

distinction between said indicators.

I preferably use numerals for forming the indicators for the separate circuits, and at Fig. 17 I have shown a suitable index or 80 sheet H as provided with combination indicators h  $h^1$ ,  $h^2$ ,  $h^3$ ,  $h^4$   $h^5$ , for representing the respective circuits leading to the stations A<sup>2</sup> B<sup>2</sup> C<sup>3</sup>. The subscribers for these stations may be John Jones, James Jackson, and 85 Jacob Johnson, and the indicators for the circuits leading from said stations preferably consist of the following combinations 1-2, 2-3, 3-11. At Figs. 3 and 5, I have shown the switching apparatus a and the 90 controlling device e in their positions assumed when connecting with the line conductors A A1 the circuit represented by the combination indicator 3-11. Consequently, the movable terminal  $a^3$  is shown at Fig. 3, 95 as engaged with the eighth contact-terminal 8/C<sup>7</sup> of the series engaged by said movable terminal, and the operating pieces  $e^8$   $e^9$  are shown at Fig. 5, as arranged in the third and eleventh apertures  $e^{41}$  of the support or disk 100  $e^{37}$ . The line conductor  $A^1$  is preferably connected to the first contact-terminal A7 of the series engaged by the movable terminal  $a^1$  and as the contact-terminals engaged by the 30 movable terminals of the switching appa- 105 ratus a are preferably numbered consecutively, it requires eleven advances or steps of the rack  $a^{10}$  and the operating pieces  $e^8 e^9$  to connect the line conductors A A<sup>1</sup> with the grounded conductor of the 68th circuit, 110 which is provided with the fixed contactterminal 8/C7, and is designated by the combination indicator 3-11. It also requires only sixty advances or steps of said rack and operating pieces to connect the line conductors A A1, with the 900th circuit designated by the combination indicator 30-60.

The mechanism for moving the operating pieces  $e^8$   $e^9$ , preferably consists of a spring  $e^{43}$  suitably connected to the support or disk 120  $e^{37}$ , and an escapement for controlling the movement of said support or disk. The movement of said support or disk. spring  $e^{43}$  preferably encircles a sleeve  $e^{44}$ loosely mounted on a rocking spindle  $e^{45}$ having its opposite ends journaled in the 125 front and rear walls of the frame  $e^1$ . One end of the spring  $e^{43}$  is fixed to the rear wall of the frame  $e^1$ , and its opposite end is secured to a downwardly extending toothed arm  $e^{48}$  fixed to the leeve  $e^{44}$  and engaged 130

with the gear  $e^{27}$ , previously mentioned. A depending arm  $e^{47}$  is fixed to the spindle  $e^{45}$ and its free end detachably engages a shoulder projecting from the arm  $e^{46}$ , in order 5 that the spindle and sleeve  $e^{45}$   $e^{44}$  may move simultaneously in one direction, and independently in the opposite direction. The free end of the spindle  $e^{45}$  projects beyond the front wall of the frame e1 and is pro-10 vided with a lever  $e^{48}$ , which is normally arranged in its position assumed at Figs. 5 and 6.

The lever  $e^{48}$  is tilted upwardly after the operating pieces e<sup>8</sup> e<sup>9</sup> are suitably arranged 15 for calling a desired circuit, and is then returned to its normal position. As the lever  $e^{48}$  is tilted upwardly the arm  $e^{47}$  engages the arm  $e^{46}$  and moves the same against the action of the spring  $e^{43}$  until a suitable stop 20  $e^{49}$  limits the onward movement of the arm  $e^{46}$ . The spring  $e^{43}$  is thus tensioned and the arm  $e^{46}$  is restrained from return movement by the escapement for the support or disk  $e^{37}$ . The movement of the arm  $e^{48}$  25 effected by the lever  $e^{48}$ , is, however, sufficient to completely revolve the gear  $e^{27}$  meshing therewith, and thus detachably engage a tooth  $e^{50}$  projecting from said gear with a movable dog  $e^{51}$  secured to the support or 30 disk  $e^{37}$ . The tooth  $e^{50}$ , and the dog  $e^{51}$  are so constructed and arranged, that the gear  $e^{27}$  when actuated by the arm  $e^{47}$  is free to move in the same direction as indicated by arrow 3, Fig. 10, without rotating the support or disk  $e^{37}$ , and is afterward prevented from returning to its normal position, except when the escapement for the support or disk  $e^{37}$  permits the operating pieces  $e^8$   $e^9$ to continue their onward movement as effect-<sup>40</sup> ed by the spring  $e^{43}$ . After the gear  $e^{27}$  has been completely revolved, as described, and has commenced its return movement, the lever e48 is prevented from again revolving said gear in the same direction as that indicated by arrow 3, Fig. 10 until the terminal support  $e^7$  has made a complete revolution. The means for preventing such movement of the gear  $e^{27}$  may be of any desired form, size, and construction, but it preferred. ably consists of a pivoted stop  $e^{52}$ , which engages the teeth of the gear  $e^{27}$ , and is forced out of engagement with said gear when the terminal support  $e^7$  is in its normal position, by a cam  $e^{53}$  secured to said 55 terminal support.

described for tensioning the spring  $e^{43}$ , it is returned to its normal position, and this movement of the lever  $e^{48}$  from and to its normal position is utilized to actuate the escapement for the terminal support  $e^{\tau}$  and thus permit the first advance or step of said

respectively to the sleeve  $e^{44}$ , and the spindle  $e^{34}$ . As the lever  $e^{48}$  is tilted upwardly the arm  $e^{54}$  engages the arm  $e^{55}$  and rocks the escapement dogs  $e^{30}$   $e^{31}$  in one direction, and as the lever  $e^{48}$  is reversely tilted said escape- 70 ment dogs are moved in the opposite direction by the spring  $e^{36}$ , thus permitting the first advance or step of the terminal support The arm e<sup>55</sup> just described is engaged by a suitable stop when the movable parts 75 of the controlling device e are in their normal position. Consequently, when a calling current is passed through the line conductor A1 for operating the signal A4, the magnet  $e^{21}$  which is simultaneously energized 80 is unable to attract its armature, and the escapement for the terminal support  $e^{\tau}$  is not actuated to permit an advance or step of said support. This stop may be of any desirable form, size, and construction, but 85 it preferably consists of an arm  $e^{56}$  fixed to the arm  $e^{46}$  and normally engaged with the arm  $e^{55}$ , Fig. 10.

The escapement for controlling the movement of the operating pieces  $e^8$   $e^9$ , prefer- 90 ably consists of a toothed wheel  $e^{57}$  and escapement dogs  $e^{58}$   $e^{59}$  actuated by the magnet  $e^{23}$ . The wheel  $e^{57}$  is supported on a shaft provided with a pinion  $e^{60}$  meshing with gear teeth formed upon the periphery 95 of the support or disk  $e^{37}$  and the escapement dogs  $e^{58}$   $e^{59}$  are of any suitable construction capable of permitting successive step by step movements of the wheel  $e^{57}$ . As here illustrated, the dogs  $e^{58}$   $e^{59}$  resemble the ordinary escapement dogs of a typewriter carriage, and one dog  $e^{58}$  is fixed to the armature of the magnet  $e^{23}$  and the other dog  $e^{59}$ is pivoted to said armature. As the magnet  $a^{23}$  is energized, the dog  $e^{58}$  is withdrawn 105 from operative position and the wheel  $e^{57}$  completes an advance movement or step, and is restrained from further movement by the  $dog e^{59}$ . The magnet  $e^{23}$  is then deenergized and the armature therefor is returned to its 110 normal position by a suitable spring, thus engaging the dog  $e^{58}$  with the tooth of the wheel  $e^{57}$ , previously engaged by the dog  $e^{59}$ . As the shaft provided with the wheel  $e^{57}$  is geared to the support or disk carrying the 115 operating pieces  $e^8$   $e^9$ , said operating pieces are permitted to make an advance movement or step upon each movement or step of the wheel  $e^{57}$ .

The switching apparatus a and the con- 120 After the lever e48 is tilted upwardly as trolling device e are preferably of such construction that their synchronism is always maintained, but I have deemed it advisable to so construct said controlling device that the position of the operating pieces  $e^8$   $e^9$  125 may be adjusted by the subscriber, should the circuit called not correspond to the one support. This result may be accomplished represented by the indicators or hands  $e^{38}$   $e^{39}$ . by any suitable mechanism, but I preferably This adjustment is effected by securing the 65 use the spring  $e^{36}$  and arms  $e^{54}$   $e^{55}$  secured toothed escapement wheel  $e^{57}$  to a sleeve  $e^{61}$  130

movable lengthwise on the shaft provided with the pinion  $e^{60}$  for permitting disengagement of said toothed wheel and the escapement dog  $e^{58}$ . A suitable spring  $e^{62}$  holds 5 the sleeve  $e^{61}$  in its normal position, and an aperture  $e^{63}$  in the lower part of the frame  $e^1$  permits engagement of said sleeve. The subscriber is enabled to readily determine when the operating pieces  $e^{8}$   $e^{9}$  have reached the 10 desired adjustment effected by disengaging the wheel  $e^{57}$  from the dog  $e^{58}$ , as I preferably arrange an indicator or scale  $e^{64}$  upon the outer face of the support or disk  $e^{37}$ . The graduations of the indicators  $e^{42}$   $e^{64}$  are 15 preferably similar and when the controlling device e is in its normal position, corresponding graduations of both indicators are in alinement with each other. In order that this adjustment of the operating pieces of 20 the controlling device e may be readily apparent I have shown the indicators  $e^{38}$   $e^{39}$ at Fig. 6 in their position assumed when the line conductors A A<sup>1</sup> are connected with the circuit represented by the combination 25 indicator 21—40, and it will be noted that the graduation 40 of the indicator  $e^{64}$  is alined with the graduation 0 of the indicator  $e^{42}$ . If, upon communicating with the subscriber of the circuit then connected to 30 the line conductors A A<sup>1</sup>, it should be ascertained that the circuit represented by the combination indicator 21—41 was connected to the line conductors A A1, the user of the controlling device e would then withdraw 35 the toothed escapement wheel  $e^{57}$  from engagement with the dog  $e^{58}$ , and rotate the support or disk  $e^{37}$  until the graduation 41 of the indicator  $e^{64}$  was alined with the graduation 0 of the indicator  $e^{42}$ , whereupon 40 the synchronism of the switching apparatus a and controlling device e would be established, and, upon the return of the support or disk  $e^{37}$  to its normal position the corresponding graduations of the indicators  $e^{42}$ 45  $e^{64}$  would be alined with each other.

The actuating piece  $e^{10}$  may be of any desirable form, size, and construction, and is preferably utilized to control the electric connection of the telehpone or communicator 50 of a calling circuit desiring communication with the station A<sup>2</sup>, and also to permit the terminal support  $e^7$  to make its fifth advance or step for effecting the return movement of the switching apparatus a after it has been 55 utilized to connect another circuit with said station  $A^2$ . The actuating piece  $e^{10}$  preferably consists of a lever suitably pivoted to the frame  $e^1$ , and, in order that the desired movements of the terminal support  $e^7$  may 60 be effected thereby, it is provided with upwardly projecting arms  $e^{65}$   $e^{66}$  suitably secured thereto. The arm e<sup>65</sup> is utilized to reversely move the terminal support  $e^{\tau}$  and is normally arranged directly beneath a pro-65 jection or tooth  $e^{67}$  formed or provided upon

said terminal support. The telephone or communicator A<sup>3</sup> is normally engaged with the outer end of the actuating piece  $e^{10}$  and its weight depresses said actuating piece against the action of a spring  $e^{68}$ . As the 70 telephone A3 is removed, when a call is directed to the signal A\*, the actuating piece  $e^{10}$  is immediately elevated by the spring  $e^{68}$ , thus engaging the arm  $e^{65}$  with the projection or tooth ee7 and reversely moving the 75 terminal support  $e^{\tau}$  against the action of the spring  $e^{2a}$ . As previously stated, this movement of the terminal support connects the telephone  $A^3$  in circuit with the line conductors A A1, and deenergizes the magnet 80 of the calling circuit which governs the movement of the terminal support of the controlling device of said circuit; but, as soon as the telephone A<sup>3</sup> is replaced in its normal position, the spring  $e^{26}$  returns the 85 terminal support  $e^7$  to its initial position and the signal A<sup>4</sup> is again in circuit with the line conductor A<sup>1</sup>.

When the controlling device e has operated to connect another circuit with the 90 conductors A A<sup>1</sup>, and the magnet  $e^{21}$  has been deenergized by the removal of the telephone of the called circuit, the terminal support  $e^{7}$  has been permitted to make four advances or steps for connecting the telephone 95 A<sup>3</sup> to the line conductors A A<sup>1</sup>, and at Fig. 9, I have shown said terminal support in this position. The telephone A<sup>3</sup> is then moved from its normal position upon the cessation of the operation of the signal  $A^4$ , 100 and the spring  $e^{88}$  elevates the actuating piece  $e^{10}$ , whereupon the arm  $e^{68}$  engages an arm  $e^{69}$  projecting from the shaft  $e^{34}$ , and rocks the escapement dogs e30 e31 in one direction. After the desired communication 105 has been obtained through the conductors A A¹ and the circuit connected therewith, the telephone A<sup>3</sup> is again placed in its normal position, and the actuating piece  $e^{10}$  is depressed against the action of the spring  $e^{68}$ . 110 The spring  $e^{36}$  then moves the spindle  $e^{34}$ to its normal position for rocking the escape-ment dogs  $e^{30}$   $e^{31}$  in the opposite direction, and permitting the terminal support e? to make its fifth advance or step and ground 115 the conductor A. The rack  $a^{10}$  of the switching device a then continues its onward movement, and after each advance or step thereof, the support or disk  $e^{37}$  carrying the operating pieces  $e^8$   $e^9$  is also advanced by the 120 passage of current pulsations through the magnet  $e^{23}$ .

As the support or disk  $e^{37}$  reaches its position immediately preceding its last advance or step, the operating piece  $e^{25}$  is in position to engage the arm  $e^{35}$  projecting from the spindle  $e^{34}$ . During this last advance or step, the arm  $e^{35}$  is rocked upwardly and is immediately permitted to return to its normal position upon the action 130

of the spring  $e^{36}$ , thus permitting the last  $g^{17}$   $g^{18}$ ; conductors  $f^{20}$   $f^{22}$   $g^{20}$   $g^{22}$ , magnets advance or step of the terminal support  $e^7$ ,  $f^{21}$   $f^{23}$ ,  $g^{21}$   $g^{23}$ , and resistance devices  $f^{24}$   $g^{24}$  whereupon the ground is connected to the corresponding to the like parts  $e^2$   $e^3$   $e^4$   $e^5$   $e^6$  conductor  $A^1$  and is disconnected from the conductor A. It is very desirable that the actuating piece  $e^{10}$  shall be free to effect an advance movement on step of the terminal support  $e^{18}$   $e^{16}$   $e^{17}$   $e^{18}$   $e^{20}$   $e^{22}$   $e^{21}$   $e^{23}$   $e^{24}$ . advance movement or step of the terminal support  $e^{\tau}$  only when said support is in its position assumed when connecting the line scribe the steps of the operation of the con-10 conductors A  $A^1$  for passing a current there-trolling device e and the circuits through 75 through to the signal of the connected circuit. Consequently, the arm  $e^{66}$  is held out of operative position by a shoulder  $e^{70}$  upon mal position, a calling current from a stasaid support which is provided with a flat- tion desiring to communicate with the sub-15 tened portion  $e^{71}$  that permits the arm  $e^{66}$ connection of the telephone of the calling  $e^3 e^{12}$ , the spindle  $e^{19}$ , and the conductor or circuit is dependent upon the removal of wire  $e^{20}$  to the ground, and in its passage enthe telephone of the called station from its ergizes the electric lamp  $e^{24}$ , the magnet of normal position, it is obvious that if the signal  $A^4$ , and the magnet  $e^{21}$ . During 85 subscriber for said circuit is absent when his signal is operated the signals of both vents rocking of the spindle e34 by the arm stations will continue to ring until the source  $e^{32}$ , which forms the armature of the magnet of electric energy at the main station for  $e^{21}$  and would otherwise be attracted there-25 effecting their operation is exhausted. To by, and consequently, said magnet and the 90 obviate this result I provide the controlling device e with suitable releasing mechanism which may consist, as illustrated, of a pivoted lever  $e^{72}$  having an arm  $e^{73}$  for forcing eration of the signal  $A^4$  by said calling cur-30 the escapement dogs  $e^{30}$   $e^{31}$  from operative rent, the subscriber removes the telephone  $A^3$  95 position and permitting an advance move-from the actuating piece  $e^{10}$ , whereupon the ment or step of the terminal support  $e^7$ . To spring  $e^{68}$  elevates said actuating piece, and permit this movement of the dogs  $e^{36}$   $e^{31}$ , the the arm  $e^{65}$  engages the tooth  $e^{67}$  upon the end of the arm  $e^{32}$  normally engaged with terminal support  $e^7$  and reversely moves said 35 said dogs is suitably cut away and to prevent undue movement of the support  $e^7$  a suitable stop arm  $e^{74}$  on the lever  $e^{72}$  enters a groove or cut-out in said support, and limits its movement. This groove or cut-40 out is only alined with the arm  $e^{74}$  when the terminal support  $e^{\tau}$  is in its position assumed for engaging the terminal  $e^{15}$  with the fixed brushes or terminals e3 e4 and permitting the passage of a signaling current 45 through the line conductors A A. When line conductors or wires leading therefrom. 110 the terminal support  $e^{\tau}$  is in any other position, the stop arm  $e^{74}$  engages said support  $e^{\tau}$  and prevents the movement of the lever  $e^{72}$  necessary for forcing the dogs  $e^{30}$   $e^{31}$  the terminal support  $e^{7}$  holds said arm out of 50 from operative position. It will also be its position assumed when about to engage 118 understood that the movement of the support  $e^{\tau}$  effected by the lever  $e^{\tau_2}$  is sufficient 

The controlling devices e f g are impor- 70 system, and in order that they may be thoroughly understood, I will now briefly desaid device for each operation thereof. When the controlling device e is in its nortened portion  $e^{71}$  that permits the arm  $e^{66}$  scriber at the station  $A^2$  is free to pass over 80 to assume its operative position. As the the conductors or wires  $A^1$   $A^6$ , the terminals spring  $e^{36}$  do not operate the escapement dogs  $e^{30}$   $e^{31}$  and permit an advance or forward step of the support  $e^7$ . Upon the opsupport against the action of the spring  $e^{2c}$ , 100 thereby engaging the surface terminal  $e^{18}$ with the fixed brushes or terminals  $e^4$   $e^5$ . This reverse movement of the terminal support e<sup>7</sup> deenergizes the magnet of the calling circuit which corresponds to the magnet 105  $e^{2i}$  of the device e, and the terminal support of the calling station is then automatically operated to connect the telephone of said calling station in metallic circuit with the

As the actuating piece  $e^{10}$  of the called station is elevated, the arm  $e^{66}$  carried thereby is also elevated but the shoulder  $e^{70}$  upon the arm  $e^{69}$  as presently described. When the terminals  $e^{18}$   $e^4$   $e^5$  are connected, a talkto disengage the terminals  $e^{15}$   $e^3$   $e^4$ , and ening current is free to pass over the conducting gage the terminals  $e^{17}$ ,  $e^6$ , and that is is impossible for said support to stop its advance the conductor or wire  $A^5$  to the telephone  $A^3$  120 movement when the terminal  $e^{16}$  is engaged and the conductor or wire  $A^5$  to with the fixed hypothesis at the fixed hypothesis  $A^5$  to  $A^5$ with the fixed brushes or terminals  $e^{s}$   $e^{s}$  and the line conductor or wire  $A^{1}$ . As soon as the thus connect the telephone  $A^3$  to the line conversation is finished, the subcriber replaces conductors A  $A^1$ . As previously stated, the his telephone  $A^3$  upon the actuating piece  $e^{10}$ , conversation is finished, the subcriber replaces and the spring  $e^{26}$  automatically returns the 125 terminal support  $e^{7}$  to its normal position for permitting the passage of a calling current from the line conductor or wire A1 through the magnet of the signal A4 to the 130

The controlling device e may be utilized These advances or steps of the rack  $a^{10}$  and to operate the switching apparatus a for connecting another circuit with the conductors movable terminal of the switching ap-A A<sup>1</sup>. In that event, the indicators or hands 5  $e^{38}$   $e^{39}$  are rocked on the spindle  $e^{19}$  to the desired position for permitting the operating pieces  $e^{s}$   $e^{s}$  to enter the apertures  $e^{41}$  in the support or disk  $e^{37}$  corresponding to the circuit to be connected to the conductors 10 A A<sup>1</sup>. The lever  $e^{48}$  is then tilted upwardly for tensioning the spring  $e^{43}$  and operates to engage the arm  $e^{47}$  with the arm  $e^{55}$  and rock the escapement dog  $e^{30}$  out of operative position. The lever  $e^{48}$  is then returned to 15 its normal position and the escapement dog  $e^{31}$  is rocked from its operative position by the spring  $e^{36}$ , thus permitting the first advance or step of the terminal support which separates the terminals  $e^{12}$   $e^{3}$  and engages 20 the terminals  $e^{13}$   $e^{6}$ . The ground is then disconnected from the line conductor or wire A¹ and is connected to the line conductor or wire A, whereupon a grounded current passes from the conductor or wire A through 25 the terminals  $e^6$   $e^{13}$ , the spindle  $e^{19}$ , and the conductor or wire  $e^{20}$  to the ground, and in its passage energizes the magnet  $a^{26}$  of the switching device a, and the magnet  $e^{23}$  of

the controlling device e.

The magnet  $a^{26}$  operates to connect the rack  $a^{10}$  to its motor  $D^{5}$  for effecting each advance or step of said rack and upon each advance of the rack a10 the magnet e23 withdraws the dog  $e^{58}$  from the wheel  $e^{57}$  and 35 permits the spring  $e^{43}$  to advance the escapement wheel  $e^{57}$  a single step by means of the arm  $e^{46}$ , the gear  $e^{27}$ , the support or disk  $e^{37}$ , and the pinion  $e^{60}$ . The support or disk  $e^{37}$ carrying with it the operating pieces e<sup>8</sup> e<sup>9</sup> is 40 also advanced a single step during each advance of the wheel  $e^{57}$  and is prevented from additional movement by the engagement of the dog  $e^{50}$  with one of the teeth of the escapement wheel  $e^{57}$ . The current flowing 45 along the line conductor or wire A is broken by the feeding dog support  $a^{17}$  of the switching apparatus at the commencement of each advance or step of the rack a10 effected during the connection of the conductor A to 50 the ground by the controlling device e, and, consequently as the line conductor A is broken, the magnet  $e^{23}$  is deenergized and its armature is returned by a suitable spring to its normal position and engages the dog  $e^{58}$  with the tooth of the wheel  $e^{57}$ , previously engaged by the dog  $e^{59}$ . When the feeding dog support a17 returns to its normal position after each advance step of the rack  $a^{10}$ , it closes the break in the line conductor or 60 wire A, whereupon a current again flows from said conductor or wire through the controlling device e and the conductor or wire  $e^{20}$  to the ground, and effects the corresponding advance or step of the support 65 or disk  $e^{37}$  carrying the operating pieces  $e^8$   $e^9$ .

the support e<sup>37</sup> continue until the desired paratus a has assumed its operative position. The operating piece  $e^8$  then engages 70 the arm  $e^{35}$  and cooperates with the spring  $e^{36}$  for actuating the escapement dogs  $e^{30}$   $e^{31}$ to permit the spring  $e^{26}$  to effect the second advance or step of the drum  $e^{\tau}$ . The terminals  $e^{14}$   $e^2$  are connected by said second 75 advance or step, and when the feeding dog support  $a^{17}$  engages the spring terminal  $a^{38}$  a current is free to pass from the grounded source of electric energy at the main or common station D over the line conductor or 80 wire  $A^1$  and through the terminals  $e^2$   $e^{14}$ , the spindle  $e^{19}$ , and the conductor or wire  $e^{20}$  to the ground. In its passage, this current energizes the magnet  $a^{32}$  of the switching apparatus a and the armature of said 85 magnet withdraws the stop or dog  $a^{34}$  from operative position, whereupon the dog ass connects the terminal support at to the rack  $a^{10}$ . The support  $a^4$  is then carried forward by the rack  $a^{10}$  as the same continues its onward movement owing to the continued engagement of the terminals  $e^{13}$   $e^{6}$  which are not disconnected by the second step of the terminal support  $e^{\tau}$ . Upon the first onward movement of the terminal support  $a^4$  of the  $^{95}$  switching apparatus a, the spring  $a^{36}$  is disconnected from the spring  $a^{37}$  and thereby breaks the circuit through the line conductor or wire  $A^1$ .

The advance movement of the support or 100 disk  $e^{37}$  and the rack  $a^{10}$  continues after the terminal support  $a^4$  is locked to said rack as the terminals  $e^{13}$   $e^{6}$  are still engaged, and when the movable terminal carried by said support  $a^4$  and previously forced to its oper- 105 ative position, has engaged the predetermined fixed terminal, the operating piece  $e^{9}$ engages the arm  $e^{35}$  and cooperates with the spring  $e^{36}$  for actuating the escapement dogs  $e^{50}$   $e^{31}$ , to permit the spring  $e^{26}$  to effect the 110 third advance or step of the drum  $e^7$ . The terminals  $e^{13}$   $e^6$   $e^{14}$   $e^2$  are then disconnected and the terminals  $e^{15}$   $e^3$   $e^4$  are connected, whereupon the current from the main or common station passes from the line con- 115 ductor or wire A  $e^{22}$  through the terminals  $e^4$   $e^{15}$   $e^3$  and the conductor or wire A<sup>6</sup> to the line conductor or wire A1, and then returns to the main or common station and passes through the terminal support  $a^4$ , and its 120 movable terminal in operative position, to the fixed terminal  $A^{\tau}$  engaged thereby, and thence through the normally grounded line conductor or wire of the subscriber's station with which communication is desired. In 125 its passage, this current energizes the magnets of the signals at the calling and called stations and also energizes the magnet  $e^{21}$ , and as the called subscriber removes his telephone from the actuating piece of his 130

controlling device, the terminal support or drum of said device is reversely moved and the connection to the ground of the normally grounded line conductor or wire leading to 5 said device is broken. The signals of the calling and called stations then cease their operations and the magnet  $e^{21}$  is deenergized. When the magnet  $e^{21}$  of the calling station is energized and deenergized as just 10 stated, the arm e32 utilized as the armature for the magnet e21 is attracted toward the pole of said magnet and is withdrawn therefrom by the spring  $e^{36}$ . This movement of said arm actuates the escapement dogs  $e^{30}$ 15  $e^{31}$  to permit the spring  $e^{26}$  to effect the fourth advance or step of the terminal support  $e^7$  for disconnecting the terminals  $e^{15}$   $e^3$   $e^4$  and connecting the terminals  $e^{16}$   $e^4$   $e^5$ . The talking current is then free to pass from 20 the telephone A<sup>3</sup> through the conductor or wire A<sup>5</sup> to the line conductor or wire A<sup>1</sup>, and from said telephone through the conductor or wire  $A^5$ , terminals  $e^5$   $e^{16}$   $e^4$  and conductor or wire  $e^{22}$  to the line conductor

25 or wire A. When about to communicate through the telephone A<sup>3</sup>, the subscriber removes said telephone from the actuating piece  $e^{10}$  and as the spring  $e^{68}$  elevates said actuating piece, 30 the arm  $e^{66}$  registers with the flattened portion  $e^{71}$  of the shoulder  $e^{70}$  upon the terminal support  $e^7$  and engages the arm  $e^{69}$ , thereby rocking the escapement dog  $e^{30}$  from operative position. The telephone  $A^3$  is replaced 35 upon the actuating piece  $e^{10}$  when the communication through said telephone is finished, and upon the descent of the actuating piece, the spring  $e^{36}$  reversely moves the arm  $e^{32}$  connected thereto and rocks the es-40 capement dog  $e^{31}$  from operative position, whereupon the spring  $e^{26}$  effects the fifth advance or step of the support  $e^{\tau}$ . The terminals  $e^{16}$   $e^{4}$   $e^{5}$  are then disconnected and the terminals e17 e6 are connected, thereby permitting the passage of a current from the line conductor or wire A through the terminals  $e^6$   $e^{17}$ , the spindle  $e^{19}$ , and the conductor or wire  $e^{20}$  to the ground. The passage of this current effects a continuous step 50 by step advance of the support or disk  $e^{37}$  and the rack  $a^{10}$  carrying the terminal support a4. Upon the last advance of the rack  $a^{io}$ , said rack and the terminal support  $a^{i}$ automatically return to their normal posi-55 tion, and as the support or disk  $e^{37}$  completes its revolution, the operating piece  $e^{25}$  secured thereto engages the arm  $e^{35}$  and cooperates with the spring  $e^{36}$  for actuating the escapement dogs  $e^{30}$   $e^{31}$  to permit the spring  $e^{26}$  to effect the sixth and last advance or step of the terminal support  $e^{7}$ . The controlling device e is then in its normal position and a grounded current is free to pass therethrough from the line conductor A1 to the 65 ground for operating the signal A4.

In order that the operation of my invention will be clearly understood let it be supposed that the subscriber at station A2 desires to communicate with the subscriber at station C<sup>2</sup> and that the latter circuit is represented 70 by the combination indicator 3—11. The hand e38 is rotated until the operating piece  $e^8$  is in alignment with the #3 graduation on the indicator  $e^{4^2}$  at which time the operating piece  $e^8$  is released to engage the proper 75 opening in the disk  $e^{37}$ . Then the hand  $e^{89}$ is rotated until its operating piece e<sup>9</sup> is in alignment with the #11 graduation on the indicator  $e^{42}$  whereupon the operating piece  $e^9$  is released to engage the proper opening 80 in the disk  $e^{37}$ . The lever  $e^{48}$  thereupon is elevated and depressed for the purpose of tensioning the operating spring  $e^{48}$  and this operation of lever  $e^{48}$  it will be remembered is effective through the interaction of the 85 arms  $e^{54}$  and  $e^{55}$  to operate the escapement dogs  $e^{30}$  and  $e^{31}$  to permit the rotation of the support  $e^7$  one step in its forward direction. This results in moving the brush  $e^3$  out of engagement with the terminal  $e^{12}$  which 90 disconnects the grounded conductor  $e^{20}$  from conductor  $A^1$  to prevent other lines from attempting to call station  $A^2$  while this station is engaged in originating a call.

This first advance of the terminal support 95  $e^7$  brings the brush  $e^6$  into engagement with the terminal  $e^{13}$  which it will be remembered is connected to ground through the spindle  $e^{19}$  and the conductor  $e^{20}$  and as a result of this connection a circuit is closed 100 for controlling the group selecting operation of the switch a at the main exchange. This of the switch a at the main exchange. This circuit extends from ground through the conductor  $e^{20}$ , spindle  $e^{10}$ , and terminal  $e^{13}$  connected thereto, brush  $e^6$ , magnet  $e^{23}$ , conductor A, magnet  $a^{26}$ , conductor  $a^{31}$ , interrupter spring  $a^{30}$ , support  $a^{17}$ , in its normal position, connecting spindle  $D^1$ , conductor  $D^2$ , to the source of electric energy  $D^3$ , conductor  $D^4$  to ground. This circuit is effective to cause the magnets  $e^{23}$  and  $a^{26}$  to attract their armatures. The magnet  $a^{26}$ tract their armatures. The magnet  $a^{26}$ through the rod  $a^{29}$  and pivoted arm  $a^{27}$ forces the lower end of the bar  $a^{23}$  into the notch  $d^5$  in the rocking shaft D<sup>5</sup> and this 115 shaft and the bar  $a^{23}$  elevate the support  $a^{17}$  which causes the dog  $a^{14}$  to engage a tooth of the rack  $a^{10}$  and elevate the rack one step. As soon as the support  $a^{17}$  is elevated from its normal position in engage- 120 ment with the interrupter spring  $a^{30}$ , the circuit just described is opened. The magnet  $a^{26}$  then de-energizes to permit the bar  $a^{23}$  to detach itself from the rocking shaft D<sup>5</sup> and allow the support  $a^{17}$  to return into 125 engagement with interrupter spring  $a^{30}$ , thus again completing the mentioned operating circuit. The magnet e23 of the controlling device on energization and deenergization in the manner just described, advances the disk 130

 $a^{37}$  with the operating pieces  $e^{8}$  and  $e^{9}$  one  $a^{23}$  into engagement with the notch in the step forward. The completion of the operating circuit again effects the energization of the magnets  $a^{26}$  and  $e^{23}$  and the operation 5 of relay  $\tilde{a}^{26}$  again elevates the support  $a^{17}$ to advance the rack  $a^{10}$  a second step. When the support is elevated from the spring  $a^{30}$ it opens the operating circuit of the relay  $a^{26}$  whereupon the support  $a^{17}$  again returns 10 into engagement with the spring  $a^{30}$ . The energization of the magnet  $e^{28}$  and its subsequent deenergization all of which takes place in synchronism with the operation of the magnet  $a^{26}$  is effective to advance the 15 disk  $e^{37}$  an additional step forward. Since it was assumed that the first portion of the designation of the wanted station C was "3" the magnet  $a^{26}$  and magnet  $e^{23}$  will be energized and deenergized a third time by the 20 closure of the circuit just described and this operation will be effective to advance the rack  $a^{10}$  a third step so that the cut-out  $a^{11}$  will be opposite the rod  $a^{9}$ . The rod  $a^{9}$ will then enter the cut-out  $a^{11}$  and thereby 25 permit the brush a<sup>3</sup> to move into engagement with its group of fixed terminals. At the station  $A^2$ , the disk  $e^{37}$  and its operating pieces  $e^8$  and  $e^9$  have likewise been advanced three steps so that the operating piece  $e^{s}$ 30 will engage the arm  $e^{35}$  to rock the shaft 34 and the arm  $e^{32}$  connected therewith. The arm  $e^{32}$  operates the escapement arm  $e^{30}$ to permit the support  $e^{\tau}$  to be advanced an additional step under the control of its spring 35  $e^{26}$ . This advance of support  $e^7$  brings the brush  $e^2$  into engagement with the terminal  $e^{14}$  but before the support  $a^{17}$  has ceased to engage the spring  $a^{38}$  an operatto engage the spring  $a^{32}$  an operating circuit is closed for the magnet  $a^{32}$ , from ground, conductor  $D^4$ , the source of electric energy  $D^3$ , conductor  $D^2$ , spindle  $D^1$ , support  $a^{17}$ , spring  $a^{38}$ , and off normal springs  $a^{37}$  and  $a^{36}$ , magnet  $a^{32}$ , conductor  $A^1$ , brush  $e^2$ , contact  $e^{14}$  which is electrically connected to spindle  $e^{19}$  and conductor  $e^{20}$  to ground. The magnet  $a^{32}$  is operated in this circuit to attract its armature which by means of rod  $a^{40}$  moves the stop dog  $a^{34}$  out of engagement with the notch in the dog  $a^{38}$ . The spring  $a^{39}$  forces the dog  $a^{33}$  into engage-ment with some one of the teeth on rack  $a^{10}$  C<sup>4</sup> as well as the magnets  $e^{21}$  and  $g^{21}$  con-whereby the support  $a^4$  is locked to the trolling the terminal supports e and g are

It will be recalled that the contact  $e^{13}$  is 55 of such length that the brush  $e^6$  continues to engage it even after the support has made its second step. The magnet  $a^{26}$  will therefore continue to be actuated in the circuit previously described as extending from ground, conductor D<sup>4</sup>, the source of electric energy D<sup>3</sup>, conductor D<sup>2</sup>, spindle D<sup>1</sup>, spring a<sup>30</sup>, conductor a<sup>31</sup>, magnet a<sup>26</sup>, conductor A, magnet e<sup>23</sup>, brush e<sup>6</sup>, contact e<sup>13</sup>, spindle e<sup>19</sup>, conductor e<sup>20</sup> to ground. Under the control conductor  $e^{20}$  to ground. Under the control the action of the spring  $g^{26}$  thereby bring65 of this circuit the magnet  $a^{26}$  forces the bar ing the terminal  $g^{18}$  into engagement with 130

rocking shaft  $D^5$  to rotate the support  $a^{17}$  causing the dog  $a^{14}$  to advance one step, the

rack  $a^{10}$  and the support  $a^4$  now locked to it.

When the support  $a^{17}$  disengages the 70 spring  $a^{30}$  the magnets  $a^{26}$  and  $e^{23}$  deenergize, with the result that the energization and deenergization of the magnet  $e^{23}$  advance the disk  $e^{37}$  and the operating pieces e<sup>g</sup> and e<sup>g</sup> one step. Since it was assumed 75 that the second portion of the designation of the wanted station  $e^2$  was "11" the magnets  $a^{26}$  and  $e^{23}$  will be energized and deenergized eight times in the manner just described. It will here be noted that the 80 number of impulses transmitted for the second portion of the designation of the wanted number is equal to the number of steps between the hands  $e^{38}$  and  $e^{39}$ . In the present instance, since the hand  $e^{38}$  is positioned 85 opposite graduation #3 and since the hand is positioned opposite graduation #11, the distance between the two hands is equal to eight steps, therefore the rack and the support locked to it are advanced eight 90

When the hand  $e^{39}$  and its operating piece e9 have thus been advanced eight steps, the operating piece  $e^9$  will engage the arm  $e^{35}$ to actuate the escapement dogs  $e^{30}$  and  $e^{31}$  95 and thereby advance the support  $e^{\tau}$  an additional step. This will bring the brushes e<sup>3</sup> and e<sup>4</sup> into electrical connection through the contact  $e^{15}$ . The signal bells A<sup>4</sup> and C<sup>4</sup> at the calling and called stations are thus 100 connected in a ringing circuit which may be traced from the grounded conductor D4, the source of electrical energy  $D^3$ , conductor  $D^2$ , spindle  $D^1$ , support  $a^{17}$ , spring  $a^{30}$ , conductor  $a^{31}$ , magnet  $a^{26}$ , conductors  $a^{31}$ , and  $a^{30}$ , conductors  $a^{31}$ , magnet  $a^{26}$ , conductors  $a^{31}$ , brush  $a^{4}$ , contact  $a^{15}$ , brush  $a^{3}$ , conductor  $a^{6}$ , resistance lamp  $a^{24}$ , magnet of the bell  $a^{4}$ , magnet  $a^{21}$ , conductor  $a^{10}$ , conductor A<sup>10</sup>, conducting bar  $a^6$ , brush  $a^3$  now in engagement with the fixed terminal connected 110 to conductor C<sup>8</sup>, contact C<sup>9</sup>, conductors C<sup>10</sup> and  $C^1$  winding of the magnet  $g^{21}$ , magnet of bell  $C^4$ , resistance lamp  $g^{24}$ , conductor  $C^6$ , brush  $g^3$ , contact  $G^{12}$  and conductor  $g^{20}$  to ground. The magnets of the bells  $A^4$  and  $B^4$  and energized in this circuit, but the magnet  $a^{26}$ does not receive sufficient current to be energized. The bells A4 and C4 continue to ring 120 until the called party at station C2 answers, or until the calling party at station A2 abandons the call in the manner that has already been described. When the called party at station  $C^2$  answers by removing his com-municator  $C^3$  from its support the pawl  $g^{65}$ engages tooth  $g^{67}$  upon the terminal support  $g^7$  and reversely moves the support against

in the talking circuit at the called station. The reverse movement of the support  $g^{\tau}$  interrupts the ringing circuit just described 5 and thereby effects the deenergization of the magnet  $e^{21}$  which operates the escape-ment dogs  $e^{30}$  and  $e^{31}$  to advance the support  $e^7$  so that the brushes  $e^4$  and  $e^5$  are electrically connected by the surface termi-10 nal  $e^{16}$ . It will thus be seen that by the response of the called party at station C<sup>2</sup> the ringing of the bells at the calling and called stations is immediately stopped and the controlling devices of the calling station and 15 called stations are advanced to complete a talking circuit between them. The talking circuit extends from the communicator As, conductors A5 and A1, conductor A10, conducting bar a<sup>6</sup> through the now operated 20 brush  $a^3$ , through the fixed terminal corresponding to the called station, conductor C<sup>8</sup>, contact C<sup>9</sup>, conductors C<sup>10</sup>, C<sup>1</sup>, C<sup>5</sup>, communicator C<sup>3</sup>, brush g<sup>5</sup>, surface terminal g<sup>18</sup>, brush g<sup>4</sup>, conductor g<sup>22</sup>, conductor C, winding of the magnet e<sup>26</sup>, conductor e<sup>31</sup>, spring  $c^{30}$ , support  $c^{17}$ , conducting spindle  $D^1$ , support  $a^{17}$ , spring  $a^{30}$ , conductor  $a^{31}$ , magnet  $a^{26}$ , conductor A, conductor  $e^{22}$ , brush  $e^4$ , contact  $e^{16}$ , brush  $e^5$ , to the communicator  $A^3$ . In the event that the called party at station C<sup>2</sup> is engaged originating a call or in conversation at the time when the calling

party at station A<sup>2</sup> attempts to connect therewith, it will be impossible to close the 35 ringing circuit since the brush  $g^3$  will be out of engagement with the grounded contact  $g^{12}$ . It will also be impossible to call the station  $A^2$  while it is attempting to originate a call since the brush  $e^3$  is likewise out of engagement with the grounded contact  $e^{12}$ .

My invention will now be readily understood upon reference to the foregoing description and the accompanying drawings, and it will be evident to one skilled in the 45 art that it is particularly simple, practical, and effective, and possesses features of great advantage and merit. It will also be understood that without departing from the spirit

of my invention considerable change may be made in the switching apparatus and the controlling devices, as clearly indicated in the foregoing description.

Having thus fully described my invention, what I claim as new and desire to se-

55 cure by Letters Patent, is:-

1. An electric exchange system comprising a main station, a series of circuits leading to the main station, a switching appa-60 circuit with any of the others, a current generator at the main station for controlling the operation of the switching apparatus, a subscriber's controlling device for govern-65 generator, and means at the main station ing apparatus at the main exchange ar- 13

the brushes g<sup>4</sup> and g<sup>5</sup> to close a break point connected to the switching apparatus and to the circuit connecting said controlling device and switching apparatus, for automatically governing the operation of the controlling device, substantially as and for the 70

purpose described.

2. An electric exchange system comprising a main station, a series of circuits leading to the main station, a subscriber's controlling device connected to one circuit for 75 controlling the passage of the current therethrough, a switching apparatus connected to said one of the circuits for connecting the same with the other circuits, a motor connected to the switching apparatus 80 for intermittently actuating the same, and means at the main station connected to the switching apparatus and to the circuit connecting said controlling device and switching apparatus, and operated by each ad- 85 vance movement or step of the switching apparatus for governing the operation of the controlling device, substantially as and for the purpose specified.

3. An electric exchange system compris- 90 ing a series of circuits, a switching apparatus connected to each of said circuits for connecting one circuit with any of the other circuits, a continuously moving motor for actuating the switching apparatus, normally 95 disconnected therefrom, connections between the switching apparatus and the motor for controlling the movement of the switching apparatus, a controlling device connected to said one of the circuits for gov- 100 erning the operation of the connections, and means connected to the switching apparatus for governing the operation of the controlling device, substantially as and for the pur-

pose set forth.

4. An electric exchange system comprising a series of circuits provided with longitudinally extending fixed contact-terminals, each contact-terminal being connected to one of the circuits, a series of switching 110 apparatus provided with movable terminals connected to corresponding circuits and movable across the contact-terminals, whereby each switching apparatus connects the corresponding circuit with any of the other 115 circuits, a motor for actuating the switching apparatus, connections between each switching apparatus and the motor for intermittently connecting each switching apparatus to the motor, electro-magnets for op- 120 erating said connections, and means for automatically breaking the circuits to the electromagnets during the operation of the connecratus at the main station for connecting one tions between the switching apparatus and the motor, substantially as and for the pur- 12 pose set forth.

5. An electric exchange system comprising a main exchange, a plurality of out-going the passage of the current from said ing circuits, an incoming circuit, a switch-

ranged for a plurality of separate selective operations for interconnecting said incoming circuit with any of said out-going circuits, a variably operable sender for con-5 trolling said switching apparatus over said incoming circuit, a progressively movable circuit-controlling switch associated with said incoming circuit for changing the relation of said sender to said switching ap-10 paratus to permit said sender to control a plurality of separate selective operations of said switching apparatus and means connected to the switching apparatus for governing the operation of said sender.

6. An electric exchange system comprising a main station, a series of metallic circuits leading to the main station and provided with sub-stations, a current generator at the main station connected to one of the circuits 20 for passing a current therethrough, a subscriber's controlling device at the sub-station connected to said one of the circuits for automatically governing the passage of the current therethrough, a switching apparatus

25 at the main station for connecting said circuit with the other circuits, and means at the main station connected to the switching apparatus and to the circuit connecting said controlling device and switching apparatus for automatically governing the operation of the controlling device, substantially as and for the purpose set forth.

7. An electric exchange system comprising a series of metallic circuits, an automatic 35 switching apparatus for connecting one of the circuits with the others, said switching apparatus being provided with separate electrically controlled mechanisms connected to the respective conductors of said one of the 40 circuits for controlling the operation of the switching apparatus, and an automatically operating controlling device for governing the passage of the current through said conductors to said mechanisms, and thereby con-45 trolling the operation of the switching apparatus, substantially as and for the purpose specified.

8. An electric exchange system comprising a series of metallic circuits having corre-50 sponding wires normally connected and their opposite wires normally disconnected, and provided with longitudinally extending fixed contact terminals, a series of switching apparatus provided with movable terminals 55 connected to the normally disconnected wires of the circuits and movable across the contact terminals for connecting said disconnected wires, whereby each switching apparatus connects the corresponding circuit with 60 any of the other circuits, a motor for actuating the switching apparatus, connections between each switching apparatus and the motor for independently connecting each ratus to the motor, an electro-magnet for switching apparatus to the motor, electro- operating said connections, and means for 65 magnets for actuating said connections, and breaking the circuit to the electro-magnet 130

means for breaking the circuits to the electro-magnets when the corresponding switching apparatus are connected to the motor, substantially as and for the purpose described.

9. An electric exchange system comprising

a series of metallic circuits, each provided with a fixed longitudinally extending contact-terminal, a series of switching apparatus each provided with a terminal con- 75 nected to the corresponding circuit, and movable across the contact-terminals for connecting the corresponding circuit with any of the other circuits, separate electrically controlled mechanisms connected to the respec- 80 tive conductors of each circuit for controlling the operation of the corresponding switching apparatus, controlling devices connected to the circuits for automatically governing the passage of the current to said mechanisms, and means connected to the switching apparatus for governing the operation of the controlling devices, substantially as and

for the purpose specified.

10. An electric exchange system compris- 90 ing a main station, a series of circuits leading to the main station and provided with sub-stations, a current generator at the main station connected to one of the circuits for passing a current therethrough, a control- 95 ling device at the sub-station connected to said one of the circuits for automatically governing the passage of the current therethrough, a switching apparatus at the main station for connecting said circuit with the 100 other circuits, said switching apparatus being provided with a member movable from its normal position for effecting the desired connection made by the switching apparatus and automatically returnable to its normal 105 position, means connected to the switching apparatus and the circuit connecting said controlling device and switching apparatus for automatically governing the operation of the controlling device, a stop for nor- 110. mally preventing the return movement of said member, and means connected to said member and automatically operated thereby for forcing the stop from operative position and permitting return movement of the 115 member, substantially as and for the purpose specified.

11. An electric exchange system comprising a series of circuits, a switching apparatus connected to one of the circuits, and 120 provided with a plurality of terminals for connecting said circuit with the others, mechanism for forcing the desired terminal into operative position, a motor for actuating the switching apparatus, connections be- 125 tween the switching apparatus and the motor for connecting the switching appa-

to the motor, substantially as and for the

purpose set forth.

12. An electric exchange system compris-5 ing a nain station, a series of metallic circuits, leading to the main station and each provided with a fixed longitudinally extending contact-terminal, a series of switching apparatus at the main station each pro-10 vided with a terminal support, a plurality of terminals independently movable on said support and movable across the fixed contact-terminals, for connecting the corresponding circuit with the other circuits, 15 means for electrically connecting the movable terminals to the corresponding circuit, and with separate electrically controlled mechanisms connected to the respective conductors of said circuit for controlling the operation of the switching apparatus, substantially as and for the purpose described.

13. An electric exchange-system comprising a series of circuits and a switching apparatus connected to one of the circuits and 25 provided with a movable terminal-support, a plurality of terminals carried by the movable terminal-support for connecting said one of the circuits with any of the other circuits, said terminals being movable independently into their operative position and being normally electrically disconnected from said one of the circuits, and means for electrically connecting the terminal to said one of the circuits, substantially as and for

35 the purpose described.

14. An electric exchange system comprising a series of circuits each provided with a fixed longitudinally extending contact-terminal, a series of switching apparatus con-40 nected to the circuits and each provided with a terminal support, a plurality of terminals independently movable on said support and movable across the fixed contactterminals for connecting the corresponding 45 circuit with the other circuits, said terminals being electrically disconnected from the corresponding circuits, and means for electrically connecting the terminals to their supports, substantially as and for the purpose 50 described.

15. An electric exchange system comprising a main station, a series of circuits leading to the main station and each providedwith a fixed longitudinally extending con-tact-terminal, a series of switching apparatus connected to the circuits and each provided with a plurality of terminals movable across the fixed contact-terminals and connected to the corresponding circuit for con-60 necting said circuit with the other circuits, a subscriber's controlling device connected to one of the circuits for governing the passage of the current therethrough, and means at the main station connected to the corre-65 sponding switching apparatus and to the the purpose set forth.

when the switching apparatus is connected circuit connecting said controlling device and switching apparatus for automatically governing the operation of said controlling device, substantially as and for the purpose

specified.

16. An electric exchange system comprising a main station, circuits leading to the main station and having a series of common fixed terminals, a switching apparatus for each circuit said switching apparatus being 75 located at the main station and being each provided with separate electrically operated mechanisms connected to respective conductors of the corresponding circuit, and a controlling device for each circuit connected 80 to the respective conductors of said circuit and provided with electric-conducting means for controlling the passage of the currents over said conductors and governing the operation of said mechanisms, and connected 85 adjustable operating pieces for automatically regulating the operation of the electricconducting means, substantially as and for the purpose set forth.

17. An electric exchange system compris- 90 ing a main station, a series of circuits leading to the main station, a switching apparatus at the main station for connecting one of said circuits to the other circuits said switching apparatus being provided with 95 separate electrically operated mechanisms connected to respective conductors of said one of the circuits, and a controlling device connected to said circuit and provided with electric-conducting means for controlling the 100 passage of the currents over said conductors and governing the operation of said mechanisms, connected operating pieces adjustable toward and away from each other for automatically regulating the operation of the 105 electric-conducting means for controlling the hands for indicating the position of the connected operating pieces, substantially as and

for the purpose specified. 18. An electric exchange system compris- 110 ing a main station, a series of circuits leading to the main station, a switching apparatus at the main station for connecting one of said circuits to the other circuits said switching apparatus being provided with 115 independent electrically operated mechanisms connected to respective conductors of said one of the circuits, and a controlling device connected to said circuit and provided with electric-conducting means for 120 controlling the passage of the current over said circuit, and effecting the independent operation of said mechanisms, connected operating pieces adjustable toward and away from each other for automatically regulat- 125 ing the operation of the electric-conducting means, and an indicator having graduations arranged in proximity to the path of said operating pieces, substantially as and for

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19. An electric exchange system comprising a main station, a series of circuits leading to the main station, a switching apparatus for connecting one of said circuits to the other circuits provided with electrically operated mechanism connected to said one of the circuits, a controlling device connected to said circuit and provided with indicating graduations, electric-conducting means 10 for controlling the passage of the current over said circuit and governing the operation of said mechanism, independently adjustable operating pieces for automatically regulating the operation of the electric-con-15 ducting means, mechanism for automatically moving the operating pieces, means at the main station for controlling the operation of said mechanism, and indicators or hands movable in proximity to the graduations for 20 indicating the position of the operating pieces, substantially as and for the purpose specified.

20. An electric exchange-system comprising a series of circuits provided with sub-25 stations having signals, a main station provided with a switching apparatus for connecting one circuit with the others, a current-generator at the main station, and means at one of the sub-stations for com-30 pleting the circuit between the generator and the switching apparatus, for automatically breaking the circuit between the generator and the switching apparatus and for automatically completing the circuit be-35 tween the generator and the signal at another of the sub-stations, substantially as

and for the purpose set forth.

21. An electric exchange-system comprising a main station, a series of circuits pro-40 vided with sub-stations having signals, a current-generator at the main station, a switching apparatus at the main station for connecting a line-conductor of one of the circuits to a line-conductor of a second cir-45 cuit, having its signal in circuit with the latter conductor, and means at the sub-station of said one of the circuits for completing the circuit between the generator and a second line-conductor of said one of the cir-50 cuits, and for connecting said second lineconductor at said sub-station to the first line-conductor and completing the circuit between the generator, the first and second line-conductors of said one of the circuits, 55 said line-conductor of the second circuit, and the signal in circuit with the latter lineconductor, substantially as and for the purpose specified.

22. An electric exchange-system compris-60 ing a main station, a series of circuits provided with sub-stations having signals, a current-generator at the main station, a switching apparatus at the main station for connecting a line-conductor of one of the cir-

having its signal in circuit with the latter conductor, and a controlling device provided with means for automatically completing the circuit between the generator, a second line-conductor of said one of the circuits, 70 and the ground, and for automatically breaking said circuit and connecting said second line-conductor at said sub-station to the first line-conductor and completing the circuit between the generator, the first and 75 second line-conductors of said one of the circuits, said line-conductor of the second circuit, and the signal in circuit with the latter line-conductor, substantially as and for the purpose set forth.

23. An electric exchange-system comprising a main station, a series of circuits provided with sub-stations having signals, a current-generator at the main station, a switching apparatus at the main station for 85 connecting a line-conductor of one of the circuits to a line-conductor of a second circuit, having its signal in circuit with the latter conductor, and means at the sub-station of said one of the circuits for completing the 90 circuit between the generator and a second line-conductor of said one of the circuits, for connecting said second line-conductor at said sub-station to the first line-conductor and completing the circuit between the gen- 95 erator, the first and second-line-conductors of said one of the circuits, said line-conductor of the second circuit, and the signal in circuit with the latter line-conductor, and for breaking the latter circuit and stopping the 100 operation of the signal in circuit with said latter line-conductor, substantially as and for the purpose specified.

24. An electric exchange-system comprising a main station, a series of circuits pro- 105 vided with sub-stations having signals, a current-generator at the main station, a switching apparatus at the main station for connecting a line-conductor of one of the circuits to a line-conductor of a second cir- 110 cuit having its signal in circuit with the latter conductor, and a controlling device provided with means for automatically completing the circuit between the generator, a second line-conductor of said one of the cir- 115 cuits, and the ground, for automatically breaking said circuit and connecting said second line-conductor at said sub-station to the first line-conductor and completing the circuit between the generator, the first and 120 second line-conductors of said one of the circuits, said line-conductor of the second circuit, and the signal in circuit with the latter line-conductor, and for breaking the latter circuit and stopping the operation of the 125 signal in circuit with said latter line-conductor, substantially as and for the purpose

set forth.

25. An electric exchange-system compris-65 cuits to a line-conductor of a second circuit, ing a main station, a series of circuits pro- 13f

vided with sub-stations having signals, a current-generator at the main station, a switching apparatus at the main station for connecting a line-conductor of one of the circuits to a line-conductor of a second circuit having its signal in circuit with the latter conductor, means at the sub-station of said one of the circuits for completing the circuit between the generator and a second line-con-10 ductor of said one of the circuits, and for connecting said second line-conductor at said sub-station to the first line-conductor and completing the circuit between the generator, the first and second line-conductors of 15 said one of the circuits, said line-conductor of the second circuit, and the signal in circuit with the latter line-conductor, and means at the sub-station of the second circuit for connecting said line-conductor of 20 the second circuit at the sub-station of the second circuit to a second line-conductor of said second circuit, substantially as and for the purpose described.

26. An electric exchange-system compris-25 ing a main station, a series of circuits provided with sub-stations having signals, a current-generator at the main station, a switching apparatus at the main station for connecting a line-conductor of one of the cir-30 cuits to a line-conductor of a second circuit, having its signal in circuit with the latter conductor, a controlling device provided with means for automatically completing the circuit between the generator, a second 35 line-conductor of said one of the circuits, and the ground, and for automatically breaking said circuit and connecting said second line-conductor at said sub-station to the first line-conductor and completing the 40 circuit between the generator, the first and second line-conductors of said one of the circuits, said line-conductor of the second circuit, and the signal in circuit with the latter line-conductor, and means at the sub-45 station of the second circuit for connecting said line-conductor of the second circuit at the sub-station of the second circuit to a second line-conductor of said second circuit, substantially as and for the purpose set

27. An electric exchange-system comprising a main station, a series of circuits provided with sub-stations having signals, a current-generator at the main station, a 55 switching apparatus at the main station for connecting a line-conductor of one of the circuits to a line-conductor of a second circuit, having its signal in circuit with the latter conductor, electric communicators at the 60 sub-stations normally disconnected from the circuits, a controlling device at the sub-station of said one of the circuits for completing the circuit between the generator and a 65 cuits, and for connecting said second line- stantially as and for the purpose specified. 130

conductor at said sub-station to the first line-conductor and completing the circuit between the generator, the first and second line-conductors of said one of the circuits, said line-conductor of the second circuit, and 70 the signal in circuit with the latter line-conductor, said controlling device being provided with means for connecting the electric communicator at said station to the adjacent circuit, and means at the sub-station of the 75 second circuit for controlling the operation of said means of the controlling device, substantially as and for the purpose described.

28. The combination of a terminal-support movable lengthwise, a plurality of ter- 80 minals carried by the support and movable independently, said terminals being normally arranged in their inoperative positions, a reciprocating member movable lengthwise of the support for forcing the 85 desired terminal into operative position, and electrically controlled mechanism for forcing said support and reciprocating member into operative position, substantially as and

for the purpose set forth.

29. The combination of a series of electric circuits, a longitudinally movable support provided with a plurality of terminals for connecting one of the circuits with the other 95 circuits, said terminals being normally electrically disconnected from the corresponding circuit, a rack movable lengthwise of the support means for electrically connecting the desired terminal with the corresponding circuit, said rack being movable with said support for moving said terminal to the desired position, means for connecting the rack to the support, a dog for feeding the rack, a support for operating the dog con- 105 nected thereto with a lost motion, and electrically controlled mechanism for forcing said support and the desired terminal into operative position, substantially as and for the purpose set forth.

30. The combination of a series of electric circuits, a movable support provided with a plurality of terminals for connecting one of the circuits with the other circuits, a rack normally disconnected from the sup- 115 port for moving the same to the desired position, a magnet for automatically connecting the rack to the support, and an electrically controlled feed for the rack, substantially as

and for the purpose described.

31. The combination of a series of electric circuits, a movable support provided with a rack and a terminal for connecting one of the circuits with the other circuits, a stop for preventing return movement of the sup- 125 port, a movable operating piece for forcing the stop from operative position connected to the support whereby the operating piece is second line-conductor of said one of the cir- automatically actuated by the support, sub-

90

32. The combination of a series of electric conductors to the ground at the main stacircuits, a movable support provided with a 5 the support from its normal position, a continuously rocking shaft normally disconnected from the feed, and electrically operated mechanism for connecting the feed to the shaft and governing the movement of 10 the support, substantially as and for the purpose set forth.

33. The combination of a series of electric circuits, a movable support provided with a connections, and operating pieces for actuterminal for connecting one of the circuits 15 with the other circuits, a feed for forcing the support from its normal position, a continuously rocking shaft normally disconnected from the feed, electrically operated mechanism for connecting the feed to the 20 shaft and governing the movement of the support, and a circuit breaker for automatically breaking the circuit to said mechanism upon each movement of the support, substantially as and for the purpose set

34. The combination with a series of circuits converging at a main station, a switching apparatus for connecting one of the circuits with the other circuits, said switching 30 apparatus being provided with ground-connections at the main station for connecting both conductors of said one of the circuits to the ground, and means for breaking the circuit between one of said conductors to 35 the ground at the main station; of a connecting device for automatically controlling the operation of the switching apparatus, said connecting device comprising in its organization, a normal ground-connection, 40 mechanism for controlling the passage of a predetermined number of current-pulsations riably adjustable registers each of which is over one conductor of said one of the circuits to earth at the main station and through the ground-connection of the con-45 necting device, means for controlling the passage of one or more current-pulsations over the other conductor of said metallic circuit to earth at the main station and through the ground-connection of the con-50 necting device, and means for breaking the circuit from said conductors to the groundconnection and for connecting together both conductors of said circuit, substantially as and for the purpose described.

35. An automatic electric exchange system comprising a series of circuits converging at a main station, and each provided with a sub-station and a plurality of lineconductors, a switching mechanism having 60 a plurality of contact-terminals, a separate terminal-support for each circuit provided with a plurality of movable terminals, ground-connections for connecting conduc-

tion, a current-generator suitably connected terminal for connecting one of the circuits to the switching mechanism for controlling with the other circuits, a feed for forcing the operation of said mechanism, and connecting devices located at the sub-station of 70 the metallic circuits for controlling the operation of the current-generator, said connecting devices being each provided with ground-connections for connecting the conductors of the corresponding circuit to the 75 ground, means for making and breaking the circuit between said conductors and groundating said means, said operating pieces being capable of assuming a plurality of positions, 80 substantially as and for the purpose specified.

36. An electric exchange system comprising a main station, a series of circuits leading to the main station, switching apparatus 85 at the main station for connecting one circuit with any of the others, a source of current at the main station for controlling the operation of the switching apparatus, a controlling device including a variably oper- 90 able sender and a progressively movable sequence switch for associating said sender with one of said circuits, said controlling device controlling the passage of current from said source and means connected to the 95 switching apparatus and to the circuit connecting said controlling device and switching apparatus for automatically governing the operation of the controlling device.

37. An electric exchange system compris- 100 ing an incoming circuit, a series of out-going circuits, an automatic switch connected to said incoming circuit for connecting said incoming circuit to any of said out-going circuits, a sender having a plurality of va- 105 arranged to receive and store one portion of the designation of an out-going circuit, a multi-position progressively movable sequence switch for operatively associating-110 said registers with said incoming circuit in succession, whereby said automatic switch is selectively advanced in accordance with the setting of the first register and then selectively advanced in accordance with the 115 setting of the second register, and means connected to the automatic switch and to said incoming circuit for automatically governing the operation of said sender.

38. An electric exchange system compris- 120 ing a series of circuits provided with substations having signals, said circuits being arranged in groups, a main station provided with a switching apparatus arranged to be selectively operated to select a group of cir-cuits and to be operated subsequently to select a circuit in the selected group, an incoming circuit terminating in said switchtors of each circuit to the ground, and means ing apparatus, a source of electric energy 65 for breaking the circuit between one of said at the main station, a sender, operating 130

ing means through its various operations, said operating means being controlled by said sender over said incoming circuit and being energized from said source of electric energy, and a circuit automatically completed between said source of electric energy and the signal at the station of the selected

39. An electric exchange system compris-10 ing a series of telephone lines terminating in groups, a signal for each line, an incoming circuit, a switching apparatus connected to said incoming circuit and provided with 15 a plurality of terminals for connecting said circuit to a desired telephone line, mechanism for releasing the desired terminal into operative position with respect to a desired group of lines and for advancing the oper-20 ated terminal into engagement with the wanted line, a source of signaling current, a circuit controlling device individual to said

mechanism effective and for subsequently 25 disabling it on the selection of the wanted telephone line, means including said device for completing a signaling circuit to said wanted telephone line and for discontinuing said signaling circuit on the response of the 30 called party and means including said device

switching apparatus for rendering said

for electrically connecting the terminals of said switch to said incoming circuit.

40. An electric exchange system comprising a series of telephone lines, a substation 35 for each of said telephone lines, a terminal bank comprising groups of flat longitudi-nally extending fixed contact terminals insulatedly separated from each other, each telephone line terminating in a fixed contact ter-40 minal, a plurality of switching devices each

including a vertically movable support having a plurality of independently movable and normally inoperative terminals secured thereto, terminal releasing members on said 45 support one for each movable terminal, each

terminal-releasing member having a normal position, each switching device also including a vertically extending bar provided with a series of elements one of which is individ-

50 ual to each terminal releasing member, each succeeding element of the series being at a greater distance from the normal position of its associated terminal releasing member than the element just preceding it in the se-

55 ries, a constantly operating horizontally extending shaft common to said switching devices, an incoming circuit terminating in each switching device but normally electrically disconnected from its movable terminals, op-

60 erating means controlled over said incoming circuit to co-operate with said shaft and including said vertically extending bar and its elements which cooperate with their respective terminal releasing members for render-

means for directively advancing said switching the desired terminal operative, said op- 65 erating means subsequently advancing said terminal into engagement with the fixed terminal of a wanted telephone line, means for characterizing a wanted telephone line as busy or idle, means responsive to the idle 70 condition of a selected telephone line for signaling the same and means actuated by the response of the called party for automatically discontinuing the signaling of said selected line and electrically connecting said 75 incoming circuit to its movable terminals.

41. The combination of a plurality of horizontally extending flat contact terminals in-sulatedly mounted with contact portions exposed, said contact terminals being arranged 80 in groups spaced from each other, a plurality of vertically movable supports each having a plurality of terminals, one of said terminals being provided for each group of contact terminals, each of said terminals being 85 normally inoperative but selectively and independently movable into co-operation with its group of contact terminals, a power shaft common to and extending horizontally adjacent to said movable supports, a source of 90 power for constantly operating said shaft and means including electromagnetic means directively controlled from a distant point and co-operating with said power shaft to render the desired one of said terminals op- 95 erative and subsequently to actuate said operated terminal and its movable support selectively over its group of contact termi-

42. An electric exchange system compris- 100 ing a series of telephone lines terminating in groups, a signal for each line, an incoming circuit, a switching apparatus connected to said incoming circuit and provided with a plurality of terminals for connecting said 105 circuit to a desired telephone line, mechanism directively controlled over said incoming circuit for forcing the desired terminal into operative position with respect to a desired group of lines and for advancing the 110 operated terminal into engagement with a wanted telephone line, a source of ringing current, a circuit controlling device, means including said device for completing a signaling circuit from said source of ringing cur- 115 rent to said wanted telephone line and for. discontinuing said signaling circuit on the response of the party on said wanted tele-phone line and means including said device for electrically connecting the terminals of 120 said switching apparatus to said incoming circuit.

43. An electric exchange system comprising a series of telephone lines terminating in groups, an incoming circuit, a switching ap- 125 paratus connected to said incoming circuit and provided with a plurality of terminals for connecting said incoming circuit to a de-

forcing the desired terminal into operative position with respect to a desired group of 5 lines, and for advancing the operated terminal of said switching apparatus to said incoming circuit 10 when said switching apparatus has seized a wanted telephone line, a circuit controlling device and ALEXANDER T. BROWN.

sired telephone line, mechanism directively means including said device for electrically controlled over said incoming circuit for connecting the operated terminal of said